



IXARC Absolute Rotary Encoder

OCD-EM01B-1416-C10S-PRM



Interface

Interface	Ethernet ModbusTCP
Profile	TCP/IP, UDP, Modbus TCP (IEC 61158)
Programming Functions	Resolution, preset, complement, transmission mode: polled mode, cyclic mode, change of state
Features	Boot-Loader, Web-Applet
Transmission Rate	10 / 100 Mbit
Interface Cycle Time	≥ 10 ms

Outputs

Output Driver	Ethernet
---------------	----------

Electrical Data

Supply Voltage	10 - 30 VDC
Current Consumption	≤ 230 mA @ 10 V DC, ≤ 100 mA @ 24 V DC
Power Consumption	≤ 2.5 W
Start-Up Time	< 250 ms
Reverse Polarity Protection	Yes
Short Circuit Protection	Yes
EMC: Emitted Interference	DIN EN 61000-6-4
EMC: Noise Immunity	DIN EN 61000-6-2
MTTF	134 years @ 60 °C

Data Sheet

Printed at 27-09-2017 15:09

POSITAL

FRABA



Sensor

Technology	Optical
Resolution Singleturn	16 bit
Resolution Multiturn	14 bit
Multiturn Technology	Mechanical Gearing (no Battery)
Accuracy (INL)	$\pm 0.0220^\circ$ (14 - 16 bit), $\pm 0.0439^\circ$ (≤ 13 bit)
Code	Binary

Environmental Specifications

Protection Class (Shaft)	IP66/IP67
Protection Class (Housing)	IP66/IP67
Operating Temperature	-40 °C (-40 °F) - +85 °C (+185 °F)
Storage Temperature	-40 °C (-40 °F) - +85 °C (+185 °F)
Humidity	98% RH, no condensation

Mechanical Data

Housing Material	Steel
Housing Coating	Wet coating (RAL 9006 White Aluminium) + Cathodic corrosion protection (>720 h salt spray resistance)
Flange Type	Clamp, \varnothing 58 mm (C)
Flange Material	Aluminum
Shaft Type	Solid, Single Flat, Length = 20 mm
Shaft Diameter	\varnothing 10 mm (0.39")
Shaft Material	Stainless Steel V2A (1.4305, 303)
Max. Shaft Load	Axial 40 N, Radial 110 N
Minimum Mechanical Lifetime (10^8 revolutions with Fa/Fr)	430 (20 N / 40 N), 150 (40 N / 60 N), 100 (40 N / 80 N), 55 (40 N / 110 N)
Rotor Inertia	$\leq 30 \text{ gcm}^2$ [$\leq 0.17 \text{ oz-in}^2$]
Friction Torque	$\leq 5 \text{ Ncm}$ @ 20 °C, (7.1 oz-in @ 68 °F)
Max. Permissible Mechanical Speed	$\leq 3000 \text{ 1/min}$
Shock Resistance	$\leq 100 \text{ g}$ (half sine 6 ms, EN 60068-2-27)
Permanent Shock Resistance	$\leq 10 \text{ g}$ (half sine 16 ms, EN 60068-2-29)
Vibration Resistance	$\leq 10 \text{ g}$ (10 Hz - 1000 Hz, EN 60068-2-6)
Length	88,2 mm (3.47")
Weight	475 g (1.05 lb)

Electrical Connection

Data Sheet

Printed at 27-09-2017 15:09

POSITAL

FRABA



Connection Orientation	Radial
Connector 1	M12, Male, 5 pin, a coded
Connector 2	M12, Female, 4 pin, d coded

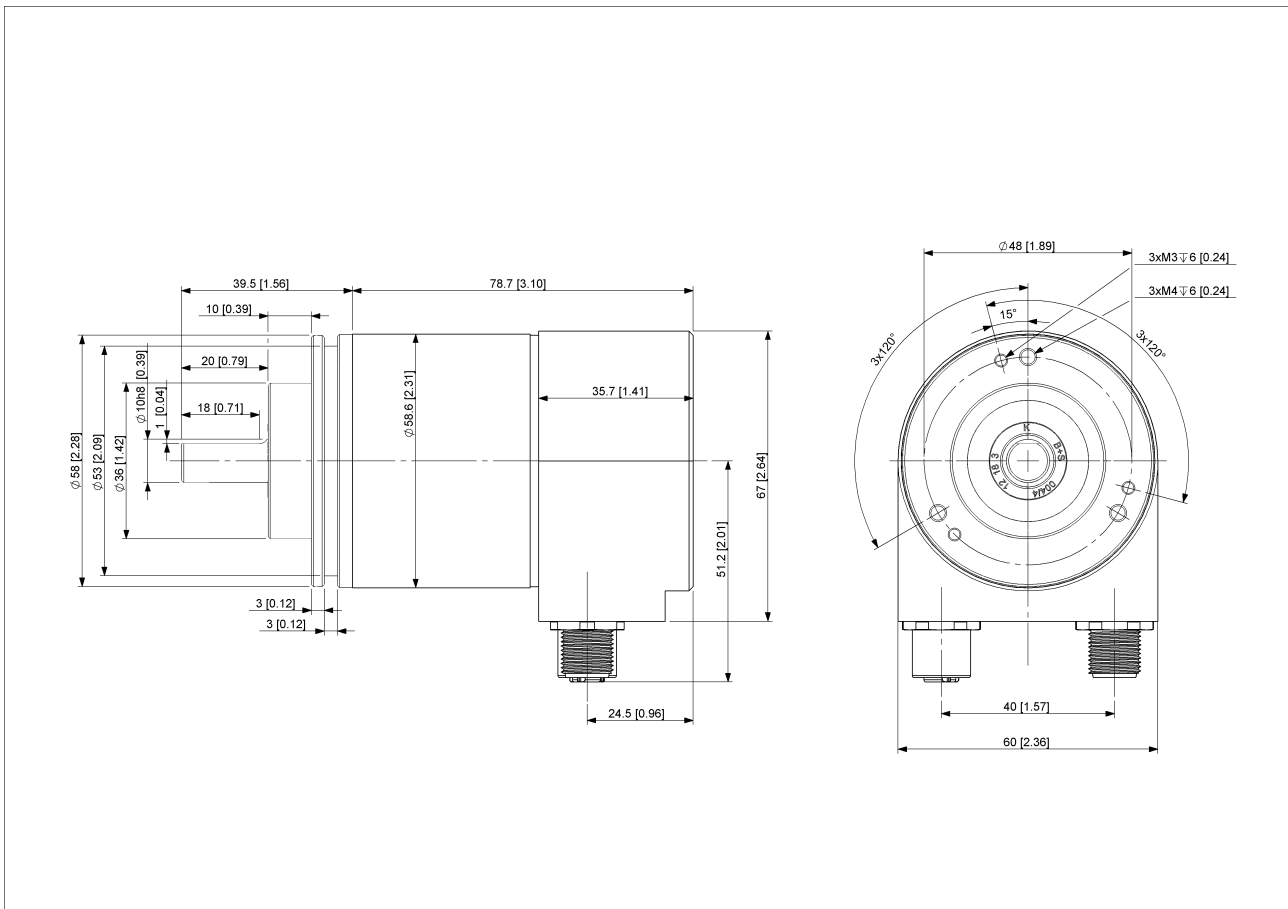
Certification

Approval	CE + cULus listed, Industrial Control Equipment
Product Life Cycle	Established

Connection Plan

SIGNAL	CONNECTOR	PIN NUMBER
Power Supply	Connector 1	1
Power Supply	Connector 1	2
GND	Connector 1	3
GND	Connector 1	4
PE	Connector 1	5
Tx+	Connector 2	1
Rx+	Connector 2	2
Tx-	Connector 2	3
Rx-	Connector 2	4

Connector-View on Encoder



Data Sheet

Printed at 27-09-2017 15:09



[2D Drawing](#)

Accessories

Connectors & Cables

10m PUR Cable, 5pin, A-Coded, f
2m PUR Cable, 5pin, A-Coded, f
5m PUR Cable, 5pin, A-Coded, f
2m PUR Cable, 4pin, D-Coded, m
10m PUR Cable, 4pin, D-Coded, m
10m PVC Cable, 4pin, D-Coded, m
2m PVC Cable, 4pin, D-Coded, m
5m PVC Cable, 4pin, D-Coded, m
M12, 4pin D-Coded, Male
M12, 5pin A-Coded, Female
5m PUR Cable, 4pin, D-Coded, m
More

Clamp Disc w/ Eccentric Hole-4pcs
Clamp Disc w/ Centred Hole-4pcs

Coupling Disc Type-10-12
Coupling Bellow Type-10-10
Coupling Bellow Type-06-10
Coupling Bellow Type-08-10
Coupling Bellow Type-10-12
Coupling Bellow Type-10-(1/4")
Coupling Bellow Type-10-(3/8")
Coupling Jaw Type-06-10
Coupling Jaw Type-08-10
Coupling Jaw Type-10-12
Coupling Jaw Type-10-(1/4")
Coupling Jaw Type-10-(3/8")
Coupling Jaw Type-10-10
Coupling Disc Type-06-10
Coupling Disc Type-10-10
More

Mounting Bracket for Clamping Flange w/ fixtures
L Mounting Bracket w/ screws



Mounting Bracket Spring Loaded f. Clamping Flange

Contact



POSITAL
Contact Us

The picture and drawing are for general presentation purposes only. Please refer to the "Download" section for detailed technical drawings. All dimension in [inch] mm. © FRABA B.V., All rights reserved. We do not assume responsibility for technical inaccuracies or omissions. Specifications are subject to change without notice.