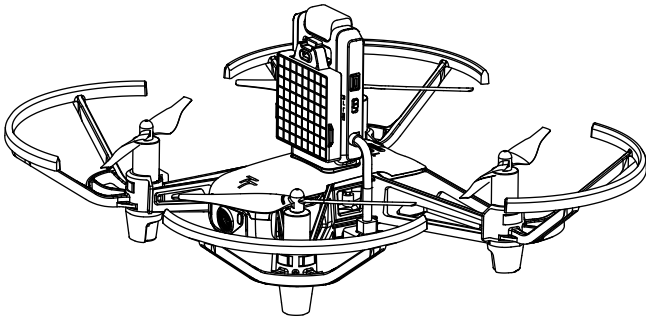# **ROBOMASTER** TT
TELLO TALENT

User Manual v1.0

2021.03

> ### 🔍 Searching for Keywords
>
> Search for keywords such as "battery" and "install" to find a topic. If you are using Adobe Acrobat Reader to read this document, press Ctrl+F on Windows or Command+F on Mac to begin a search.
>
> ### 👆 Navigating to a Topic
>
> View a complete list of topics in the table of contents. Click on a topic to navigate to that section.
>
> ### 🖨 Printing this Document
>
> This document supports high resolution printing.

Using This Manual

Legend

⊘ Warning   ⚠ Important   💡 Hints and Tips   📖 Reference

Read Before the First Flight

Read the following documents before using the RoboMaster TT:

1. RoboMaster TT User Manual
2. RoboMaster TT Quick Start Guide
3. RoboMaster TT Disclaimer and Safety Guidelines

We recommend that you watch all tutorial videos on the official DJI website https://www.dji.com/robomaster-tt and read the Disclaimer and Safety Guidelines before you fly. Prepare for your first flight by reviewing the Quick Start Guide and refer to this User Manual for more details.

Download Software

1. Download the Tello app for activation, flying the aircraft, recording footage, and updating firmware. The iOS version of the Tello app is compatible with iOS v9.0 and later. The Android version of the Tello app is compatible with Android v4.4 and later.

2. Download the Tello EDU app for programming. The iOS version of Tello EDU app is compatible with iOS v10.0 and later. The Android version of Tello EDU app is compatible with Android v4.4 and later.

3. Download and install the DJI Education Hub at http://edu.dji.com/download and update the open-source controller firmware to the latest version using RoboMaster Assistant.

Contents

Product Profile

Introduction

RoboMaster TT includes the aircraft and the expansion kit. The aircraft is a small quadcopter that features a Vision Positioning System and an onboard camera. Using the Vision Positioning System and advanced flight controller, the aircraft can hover in place and fly indoors. Advanced features like 8D Flips, EZ Shots, and Bounce mode make it even more fun to use the aircraft. The camera captures 5MP photos and streams 720p live video to the Tello app on a mobile device.

Experience DIY flight with an expansion kit that includes an open-source controller, dot-matrix display & distance-sensing module, and extension board, which can be programmed using Arduino, Scratch, MicroPython, and more. Use the Tello EDU app for programming when using a mobile device.

The max flight time of the aircraft is approx. 8 minutes with an expansion kit mounted and 13 minutes without.

Failsafe protection enables RoboMaster TT to land safely while the propeller guards can be used for enhanced safety.

* Maximum flight time was tested in windless conditions flying at a consistent 9 mph (15 kph). This value should be taken for reference only.

Aircraft Diagram
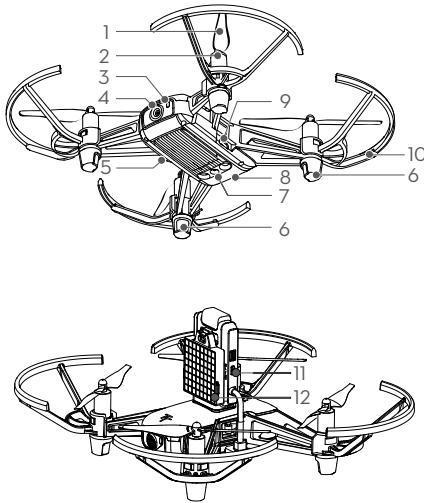
1. Propellers
2. Motors
3. Aircraft Status Indicator
4. Camera
5. Power Button
6. Antennas
7. Vision Positioning System
8. Flight Battery
9. Micro USB Port
10. Propeller Guards
11. Open-Source Controller
12. Dot-Matrix Display & Distance Sensing Module

Aircraft

The RoboMaster TT contains a flight controller, video downlink system, Vision Positioning System, propulsion system, and a Flight Battery. Refer to the aircraft diagram in the Product Profile section.

Flight Modes

The RoboMaster TT has two flight speeds that you can select when flying the aircraft manually:

- Slow (default): The maximum flight attitude angle is 9° and the maximum flight speed is 6.7 mph (10.8 kph).
- Fast: The maximum flight attitude angle is 25° and the maximum flight speed is 17.8 mph (28.8 kph).

When flying the RoboMaster TT manually the aircraft utilizes its Vision Positioning System to automatically stabilize itself. If the conditions are such that the Vision Positioning System is unavailable the aircraft automatically changes to Attitude mode.
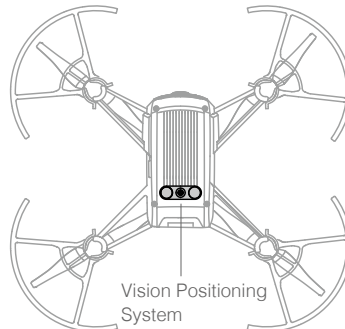
The aircraft automatically changes to Attitude mode (ATTI mode) when the Vision Positioning System is unavailable. In Attitude mode the aircraft is not able to position itself and so is easily affected by its surroundings. Environmental factors such as wind can result in horizontal shifting, which may present hazards, especially when flying in confined spaces. When the aircraft enters Attitude mode, land in a safe place as soon as possible to avoid hazards.

⚠
- To switch from Slow to Fast you must read and agree to the disclaimers and warnings that appear in the Tello app. Make sure you understand the differences between the two flight speeds.
- Failsafe Protection automatically initiates landing if the mobile device's signal is weak or is lost for 50 seconds, or the Tello app crashes.
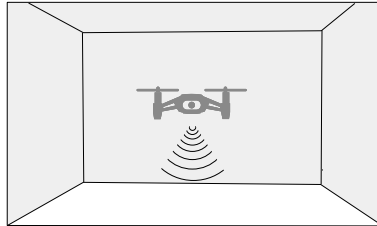
Vision Positioning System

The Vision Positioning System helps the aircraft maintain its current position. With the help of the Vision Positioning System, the aircraft can hover in place more precisely and fly indoors or outdoors in windless conditions. The main components of the Vision Positioning System are a camera and a 3D infrared module located on the underside of the aircraft.

Vision Positioning System

Using the Vision Positioning System

The Vision Positioning System is activated automatically when the aircraft is turned on. No further action is required. The Vision Positioning System is only effective when the aircraft is at altitudes of 1.0 to 98.4 ft (0.3 to 30 m) and works best at altitudes of 1.0 to 19.7 ft (0.3 to 6 m). If the aircraft is beyond this range, the Vision Positioning function may be affected, so extra caution is required.

⚠ • The performance of the Vision Positioning System is affected by the surface being flown over. The aircraft automatically changes to Attitude mode when the Vision Positioning System is unavailable. In Attitude mode the aircraft is not able to position itself. Operate the aircraft with great caution in the following situations, which may cause the aircraft to enter Attitude mode:
  a. Flying at high speed below 2 ft (0.5 m).
  b. Flying over monochrome surfaces (e.g. pure black, pure white, pure red, pure green).
  c. Flying over highly reflective surfaces.
  d. Flying over water or transparent surfaces.
  e. Flying over moving surfaces or objects.
  f. Flying in an area where the lighting changes frequently or drastically.
  g. Flying over extremely dark (< 300 lux) or bright (> 100,000 lux) surfaces or towards bright sources of light (e.g. towards sunlight).
  h. Flying over surfaces without clear patterns or texture.
  i. Flying over surfaces with identical repeating patterns or textures (e.g. tiling).
  j. Flying over small and fine objects (e.g. tree branches or power lines).
  k. Flying at high speed of over 5 m/s at 4 ft (1 m).

⚠ • If the aircraft's Vision Positioning system fails for 3 seconds when its flying altitude is above 20 ft (6 m), Failsafe Protection will automatically initiate landing. If the Vision Positioning system recovers during landing, Failsafe Protection will shut off and the aircraft will hover.
   • The Vision Positioning System may not be able to recognize patterns on the ground in very dark (< 300 lux) environments. DO NOT take off if there is a warning prompt in the Tello app telling you that the environment is too dark.
   • Keep the cameras and sensors clean at all times. Dirt or other debris may adversely affect their effectiveness.

Intelligent Flight Modes

The RoboMaster TT features Bounce mode, 8D Flips, Throw & Go, Up & Away, and EZ Shots. To use an intelligent flight mode, ensure that the aircraft's battery level is at least 50%, tap in the Tello app, then select a mode.

Bounce Mode

In Bounce mode the aircraft automatically flies up and down between 1.6 and 3.9 ft (0.5 and 1.2 m) above a flat surface. If the aircraft detects an object below it (such as your hand) it increases its altitude then continues flying up and down.

Using Bounce Mode

1. Press the power button once to turn the aircraft on. Launch the Tello app and tap ⊙ to take off.
2. Tap ⊛ and then select Bounce mode. Read the information prompt and then select **Start**. The aircraft will start flying up and down.
3. Extend your arm and place your palm 1 ft (30 cm) or more below the aircraft, keeping your palm open. The aircraft will increase its altitude then continue flying up and down.
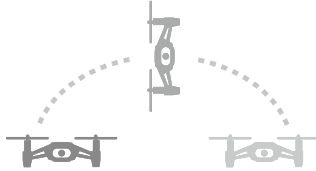4. Tap ⊗ in the Tello app any time to exit Bounce mode.
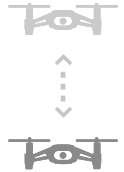
⚠ • Ensure there is sufficient space when using Bounce mode. Allow a radius of at least 7 ft (2 m) horizontally around the aircraft and allow at least 10 ft (3 m) above the aircraft.
   • Before using Bounce mode ensure that the Aircraft Status Indicator is periodically blinking green twice, indicating that the Vision Positioning System is available.
   • In Bounce mode, ensure your arm is extended and your palm is flat. DO NOT try to catch the aircraft. The distance between your palm and the aircraft should be at least 1 ft (30 cm).
   • Watch out for potential obstacles in your surrounding area (especially on the rear, left, and right sides of the aircraft) and stay clear of them to avoid accidents.
   • Be prepared to take control of the aircraft by tapping ⊗ in the Tello app to exit Bounce mode in case of an emergency.
   • Be extra cautious when flying in dark (< 300 lux) or bright (> 10,000 lux) environments.

8D Flips

In 8D Flips the aircraft automatically flips in one of eight different directions.

Using 8D Flips

1. Press the power button once to turn the aircraft on. Launch the Tello app and tap ⓧ to take off.
2. Tap ⊛ and then select 8D Flips. Read the information prompt and then select **Start**.

3. Swipe within the box shown in the app. The aircraft will flip in the direction you swipe.
4. Tap ⓧ in the Tello app any time to exit 8D Flips.

⚠ • Ensure there is sufficient space when using 8D Flips. Allow a radius of at least 7 ft (2 m) horizontally around the aircraft and allow at least 10 ft (3 m) above the aircraft.
   • Before using 8D Flips ensure that the Aircraft Status Indicator is periodically blinking green twice, indicating that the Vision Positioning System is available.
   • When using 8D Flips, the distance between you and the aircraft should be at least 3.5 ft (1 m).
   • Watch out for potential obstacles in your surrounding area (especially on the rear, left, and right sides of the aircraft) and stay clear of them to avoid accidents.
   • Be prepared to take control of the aircraft by tapping ⓧ in the Tello app to exit 8D Flips in case of an emergency.
   • Be extra cautious when flying in dark (< 300 lux) or bright (> 10,000 lux) environments.
   • Exercise caution when using 8D Flips with the expansion kit mounted.

Throw & Go

Throw & Go lets you launch the aircraft by gently throwing it into the air.

Using Throw & Go

1. Press the power button once to turn the aircraft on.
2. Tap ⊛ and then select Throw & Go.
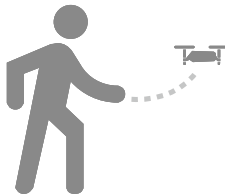
3. Place the aircraft in your palm.

4. Read the warning prompt and then tap ⊕ to start. The propellers will start spinning slowly. Gently throw the aircraft upward and horizontally away from you, keeping the aircraft horizontal as you throw it. The propellers will start spinning more quickly and the aircraft will automatically hover in place. The propellers will stop if you do not throw the aircraft within 5 seconds of the propellers starting to spin slowly.

⚠ • Only use Throw & Go in an open area and make sure that your flight path is clear of people, animals, and obstacles.
 • Throw & Go cannot be used after the aircraft has taken off.
 • Be careful when using Throw & Go and make sure you keep your fingers away from the propellers even when they are spinning slowly.
 • Hold the aircraft horizontally, and gently throw the aircraft upward and horizontally away from you. DO NOT throw the aircraft at a speed that exceeds 6 ft/s (2 m/s). DO NOT throw the aircraft at an angle to the horizontal greater than 20° and DO NOT flip the aircraft as you throw it.
 • Before using Throw & Go ensure that the Aircraft Status Indicator is periodically blinking green twice, indicating that the Vision Positioning System is available.
 • Watch out for potential obstacles in your surrounding area (especially on the rear, left, and right sides of the aircraft) and stay clear of them to avoid accidents.
 • Be extra cautious when flying in dark (< 300 lux) or bright (> 10,000 lux) environments.

EZ Shots

Using 360

In 360, the aircraft records a short video while rotating 360 degrees.

1. Press the power button once to turn the aircraft on. Launch the Tello app and tap ⊛ to take off.
2. Tap ⊛ and then select 360. Read the information prompt and then select **Start**.

3. The aircraft will rotate 360 degrees and record a video automatically. Tap ⊳ to access the video.
4. The aircraft will exit 360 once it has finished recording. You can also tap ⊗ in the Tello app any time to exit 360.

⚠ • Ensure there is sufficient space when using 360. Allow at least 2 ft (0.5 m) around the aircraft in all directions.
 • Before using 360 ensure that the Aircraft Status Indicator is periodically blinking green twice, indicating that the Vision Positioning System is available.
 • Watch out for potential obstacles in your surrounding area (especially on the rear, left, and right sides of the aircraft) and stay clear of them to avoid accidents.
 • Be prepared to take control of the aircraft by tapping ⊗ in the Tello app to exit in case of an emergency.
 • Be extra cautious when flying in dark (< 300 lux) or bright (> 10,000 lux) environments.

Using Circle

In Circle the aircraft records a short video while flying in a circle.

1. Press the power button once to turn the aircraft on. Launch the Tello app and tap ⊕ to take off.
2. Tap ✱ and then select Circle. Read the information prompt and then select **Start**.

3. The aircraft will fly in a circle around a point approximately 7 ft (2 m) in front of the aircraft nose and record a video.
4. The aircraft will exit Circle once it has finished recording. You can also tap ⊗ in the Tello app any time to exit Circle.

⚠ • Ensure there is sufficient space when using Circle. Allow a radius of at least 10 ft (3 m) around the point 7 ft (2 m) in front of the aircraft nose, and at least 10 ft (3 m) above and below the aircraft.
 • Before using Circle ensure that the Aircraft Status Indicator is periodically blinking green twice, indicating that the Vision Positioning System is available.
 • Watch out for potential obstacles in your surrounding area (especially on the rear, left, and right sides of the aircraft) and stay clear of them to avoid accidents.
 • Be prepared to take control of the aircraft by tapping ⊗ in the Tello app to exit Circle in case of an emergency.
 • Be extra cautious when flying in dark (< 300 lux) or bright (> 10,000 lux) environments.

Using Up & Away

In Up & Away the aircraft records a short video while flying upward and backward.

1. Press the power button once to turn the aircraft on. Launch the Tello app and tap ⊕ to take off.
2. Tap ✱ and then select Up & Away. Read the information prompt and then select **Start**.

3. The aircraft will record a short video while flying upward and backward.
4. The aircraft will exit Up & Away once it has finished recording. You can also tap ⊗ in the Tello app any time to exit Up & Away.

⚠ • Ensure there is sufficient space when using Up & Away. Allow at least 20 ft (6 m) behind and 3.5 ft (1 m) above the aircraft.
• Before using Up & Away ensure that the Aircraft Status Indicator is periodically blinking green twice, indicating that the Vision Positioning System is available.
• Watch out for potential obstacles in your surrounding area (especially on the rear, left, and right sides of the aircraft) and stay clear of them to avoid accidents.
• Be prepared to take control of the aircraft by tapping ⊗ in the Tello app to exit Up & Away in case of an emergency.
• Be extra cautious when flying in dark (< 300 lux) or bright (> 10,000 lux) environments.

Propellers

The RoboMaster TT uses model 3044P propellers. There are two varieties of 3044P propellers, which are designed to spin in different directions. The presence or absence of marks on the propellers indicates which type they are and therefore which motors they should be attached to.

Attaching the Propellers

Mount marked propellers on the motors with marked landing gear. Mount unmarked propellers on the motors with unmarked landing gear.

When mounting, ensure that the gap between the bottom of the propeller cap and the motor is no bigger than needed to insert the propeller removal tool.
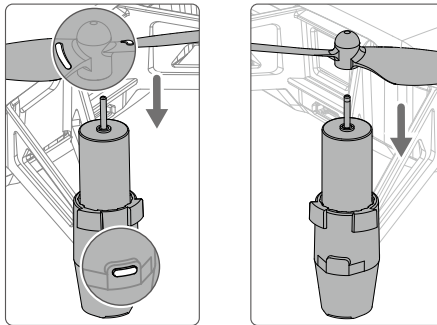
Detaching the Propellers

Insert the propeller removal tool between the propeller cap and the motor. Be sure to hold the motor while detaching the propeller.

11
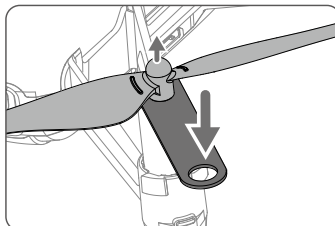
⚠ • Always detach the propellers using the propeller removal tool. DO NOT remove the propellers by hand as doing so may damage the motors and you may get seriously hurt.
- To avoid injury, stand clear of and DO NOT touch propellers or motors when they are spinning.
- Only use original propellers and DO NOT mix propeller types.
- Ensure that the propellers and motors are installed firmly and correctly before each flight.
- Ensure that all propellers are in good condition before each flight. DO NOT use aged, chipped, or broken propellers.

Propeller Guards

The Tello Propeller Guards can be used to reduce the risk of harm or damage to people or objects resulting from accidental collisions with Tello aircraft.

Mounting the Propeller Guards

Mount each of the propeller guards to the aircraft landing gear beneath the motors. Push each propeller guard inwards to wrap it around the landing gear. Make sure it clicks into position and that the protruding parts of the landing gear securely fit into the notches on the propeller guards.
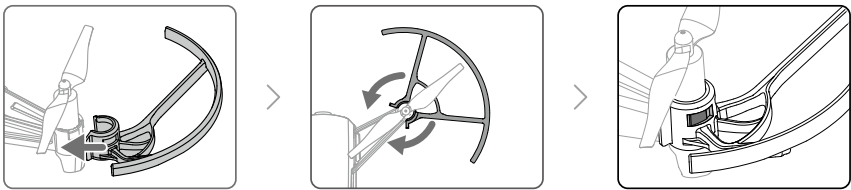
Detaching the Propeller Guards

To remove a propeller guard place your finger and thumb as shown in the figure below. With your thumb, gently apply a twisting force to the lip that protrudes from the propeller guard where it wraps around the landing gear.
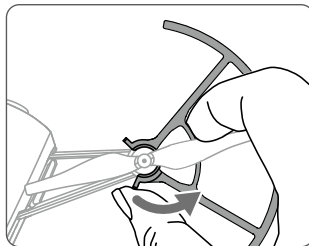
⚠ DO NOT use excessive force when removing propeller guards as doing so may damage the aircraft's arms and you may get hurt.

Flight Battery

The Flight Battery is a 3.8 V, 1100 mAh battery with charging/discharging protection.

⚠ Fully charge the Flight Battery before each flight.

Battery Features

1. Overcurrent/Overvoltage Protection: The battery stops charging if an excessive current/voltage is detected.
2. Overdischarge Protection: Discharging stops automatically to prevent excessive discharge.
3. Short Circuit Protection: The power supply is cut automatically if a short circuit is detected.

⚠ Refer to the *Tello Disclaimer and Safety Guidelines* before use. Users take full responsibility for all operations and usage.

Inserting the Flight Battery

Insert the Flight Battery into the aircraft as shown. Ensure the battery is mounted firmly.
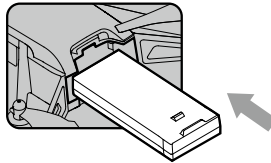
To remove the battery pull it out from the aircraft.

Charging the Flight Battery

To charge the Flight Battery connect the Micro USB port on the aircraft to a USB adapter (not provided) using a standard Micro USB cable.

Charging Time: Approx. 1 hour and 30 minutes.
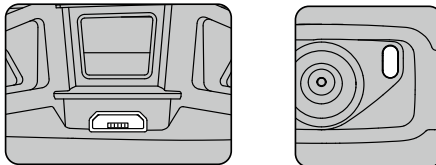
The Aircraft Status Indicator blinks blue slowly during charging. The battery is fully charged when the Aircraft Status Indicator turns solid blue. Detach the USB adapter when the battery is fully charged.

⚠️ • Always use an FCC/CE (depending on location) certified USB adapter that is rated at 5 V and 1.5 A or above.
   • Ensure the aircraft is powered off before charging. It cannot be charged when it is powered on.
   • DO NOT charge a Flight Battery immediately after flight, because its temperature may be too high. DO NOT charge a Flight Battery until it cools down to near room temperature.
   • Charge the Flight Battery in the temperature range 41° to 113° F (5° to 45° C). The ideal charging temperature range is 72° to 82° F (22° to 28° C).

💡 Before carrying the Flight Battery on an airline flight, it must be discharged to 30% or lower. To discharge the Flight Battery, fly the aircraft.

Checking Battery Level

Press the power button once to turn the aircraft on. Launch the Tello app and check the battery level in the app.
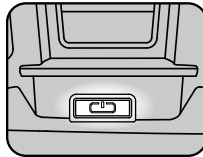
Camera

The Tello camera captures 5 megapixel photos and 720p videos. The Tello's Electronic Image Stabilization feature enables it to consistently capture clear images. The photos and videos can be viewed in the Tello app and copied to a folder in your mobile device.

Expansion Kit

Open-Source Controller

The open-source controller combines a 2.4/5 GHz dual frequency Wi-Fi module, Bluetooth module, and Arduino open-source platform. It is able to expand the features of pins such as UART, I2C, GPIO, PWM, and SPI. Experience DIY flight by customizing accessories through programs such as Arduino and MicroPython.

1. I/O Expansion Ports

Used to connect to the dot-matrix display & distance sensing module to add and expand features. Supports UART, I2C, PWM, and SPI.

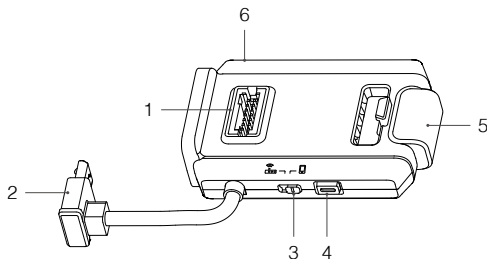| IO2	IO5	IO4	IO27	IO26	GND	3V3
IO12	IO21	IO15	IO14	IO13	GND	5V

The actual output voltage of 5 V is 4.8 V±0.2 V and of 3 V is 3.3 V±0.1 V. The maximum output current is 800 mA. Each I/O expansion port can be mapped in the program and connected to the user's expansion module. For example, the UART pin can be connected to a module that identifies QR codes so that the RoboMaster TT can be programmed to identify QR codes.

2. Micro USB Cable

Used to connect the open-source controller to a 5V/2A USB power source or the Micro USB port of the aircraft for power supply.

When connected to the Micro USB port of the aircraft, the open-source controller can be used as an expansion module. The Wi-Fi network will change to RMTT-XXXXXX when the open-source controller connects to the aircraft.

3. Switch

Used to switch between direction connection mode and router mode. Direct connection mode is where the aircraft is connected to a mobile device via Wi-Fi. Router mode is where the aircraft connected to a router.

Direct Connection Mode: Connect the mobile device to the Wi-Fi network of the aircraft named RMTT-XXXXXX.

Router Mode: Connect the aircraft to the router using the SDK. The app cannot be used to connect to the aircraft in this mode.

Toggle the switch to restart the open-source controller in router mode.

Users can test programming easily by toggling the switch back and forth to reboot the open-source controller. Note that the connection mode will depend on the final position of the switch after toggling.

4. Customizable Button

Press and hold the button to link via Bluetooth (when using the default firmware).

Press the button twice within 0.5 s to start the motors to cool down the aircraft. Press the button twice within 0.5 s again to stop the motors (when using the default firmware).

The function of the button can be customized through programming. Functions include using the button to launch programs.

5. Programmable RGB Light

The function of the RGB light is set through programming. Functions include being used as part of a light display or as a prompt.

The status of the RGB light are shown in the table below (when using the default firmware).

RGB Light Blinking Pattern	Descriptions
After powering on, the light will change color in sequence and stop	Working normally
Blinks blue	Ready for Bluetooth connection. Press and hold the customizable to link
Solid blue	Bluetooth remote controller connected

6. Micro USB Port

Used to connect to a computer. The port can be used as a debugging port for offline programs when using Arduino or MicroPython.

Used to connect to a computer to update the firmware of the open-source controller.

* The default firmware is required to connect to a Bluetooth remote controller and to use the motors to cool down the aircraft. RM Assistant can be used to restore the default firmware of the open-source controller.

Dot-Matrix Display & Distance Sensing Module
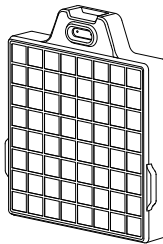
The module integrates a 8x8 dot-matrix display and a distance sensing TOF module, allowing users to generate different colors and graphics through programming. The default firmware is required to use Mind+ real-time mode or the Tello EDU app to control the dot-matrix display and RGB light.

Extension Board
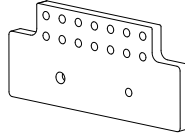
The extension board consists of 14-pin extension port to 2×7 pin, 2.54mm dual in-line package, two reserved positions for 5/3.3V power indicators, and two reserved positions for test indicators. Users can add more sensors to expand features.

SDK Mode

Enter SDK Mode
1. Make sure the aircraft and the Tello EDU app are connected.
2. Make sure the aircraft and Mind+ real-time mode are connected.
3. Make sure the default firmware of the open-source controller is being used with the Bluetooth remote controller.
4. Send the "command" command in plaintext through UDP and wait for the device to reply "ok".
5. Send the "[TELLO]" command in plaintext through the expansion kit and wait for the aircraft to reply "ok".

Exit SDK Mode
Power off the aircraft to exit SDK mode.

Status LED Descriptions

The descriptions below apply to the aircraft with or without the open-source controller mounted.
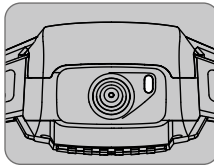
Status	Blinking Pattern	Descriptions
Normal	Blinks red, green, and yellow continuously	Powered on and performing self-diagnostic tests
	Blinks green twice repeatedly	Positioning with Vision Positioning System
	Blinks yellow slowly	No positioning with Vision Position System

| Charging	Solid blue	Charging complete
	Blinks blue slowly	Charging
	Blinks blue quickly	Abnormal status detected
SDK Mode Status	Blinks purple slowly	SDK connected
	Blinks purple quickly	SDK disconnected (no commands receive for more than 15 seconds)
Warning States	Blinks yellow quickly	Remote controller signal lost (when not in SDK mode)
	Blinks purple quickly	Remote controller signal lost
	Blinks red slowly	Low battery
	Blinks red quickly	Critically low battery
	Solid red	Critical error

Tello App

Use this app to control the camera and other aircraft functions. The app is used for configuring the aircraft, viewing photos and videos, and copying photos and videos to folders on a mobile device. In addition, the Tello app can be used for activation and firmware update.

Connect to the Aircraft

Enable Wi-Fi on the mobile device and select the network. The network is TELLO-XXXXXX when there is no expansion kit mounted and RMTT-XXXXXX when there is an expansion kit mounted. The live view will display on the screen of the mobile device once connection is complete.

Camera View
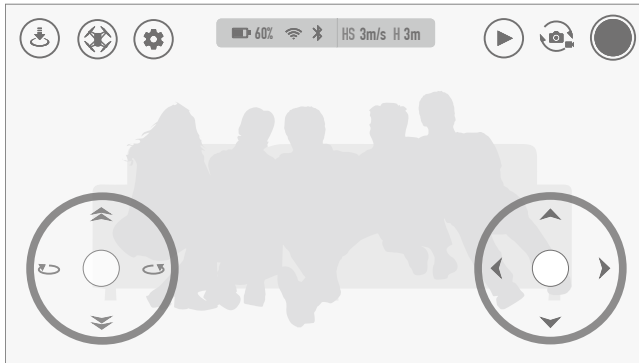
1. Auto Takeoff/Landing

   Tap ⊕ to initiate auto takeoff. Tap ⊕ to initiate auto landing.

   There are two auto landing modes: Tap to Land and PalmLand (Hand Landing). In Tap to Land the aircraft lands automatically. To use PalmLand place your palm under the aircraft, then tap to confirm and the aircraft will land on your palm and stop its motors.

   ⚠ • Do not use auto takeoff from your palm, and ensure to use auto takeoff on a flat surface.
   • Only land the aircraft on flat surfaces. DO NOT land the aircraft over water, grass or sand. When using PalmLand, ensure your palm is right under the aircraft and keep your palm flat.

2. Intelligent Flight Modes

   Tap ⊛ to select Intelligent Flight Modes.

3. Settings

   Tap ⊛ to enter the settings screen. You can adjust flight speed, VR settings, Bluetooth joystick settings, and Wi-Fi settings here.

By default the Tello does not have a Wi-Fi password. You can set a password and you can also change the Wi-Fi SSID. (To reset the Wi-Fi SSID and password to the default settings, power on the aircraft and then press and hold the power button for 5 seconds. The Tello will restart automatically.)

In the More screen the beginner guide, units of measurement, photo quality, low battery warning, and joystick settings can be configured. Tap ⬚ to calibrate the IMU or center of gravity, or to view the aircraft firmware version.

4. **Battery Level**

   🔋 60% Displays the current battery level.

5. **Wi-Fi Status**

   📶 Displays the Wi-Fi connection status.

6. **Bluetooth Status**

   ❋ Displays the Bluetooth connection status.

7. **Flight Speed**

   HS 3m/s Displays the aircraft's horizontal speed.

8. **Flight Altitude**

   H 3m Displays the altitude above the surface below the aircraft.

9. **Playback**

   Tap ▶ to enter the playback page and preview photos and videos as soon as they are captured.

10. **Photo/Video Toggle**

    Tap 🔄 to switch between photo and video recording modes.

11. **Shoot / Record Button**

    Tap ◉/● to start shooting photos or recording video.

12. **Virtual Joysticks**

    Use virtual joysticks to control the aircraft. Two modes (Mode 1 and Mode 2) are available. The default mode is Mode 2.

The virtual joysticks are used to control the aircraft's orientation (yaw), forward/ backward movement (pitch), altitude (throttle), and left/right movement (roll). The function that each virtual joystick movement performs is determined by the choice of virtual joystick mode. Two modes (Mode 1 and Mode 2) are available. The default mode is Mode 2.

In each of the two modes the Tello hovers in place at a constant orientation when both virtual joysticks are centered. Pushing a virtual joystick away from the center position performs the functions show in the figure below.

Mode 1

Left Stick   Forward   Right Stick   Up

Backward

Turn Left   Turn Right   Left   Right

Down

Mode 2

Left Stick   Up   Right Stick   Forward

Down

Backward

Turn Left   Turn Right   Left   Right
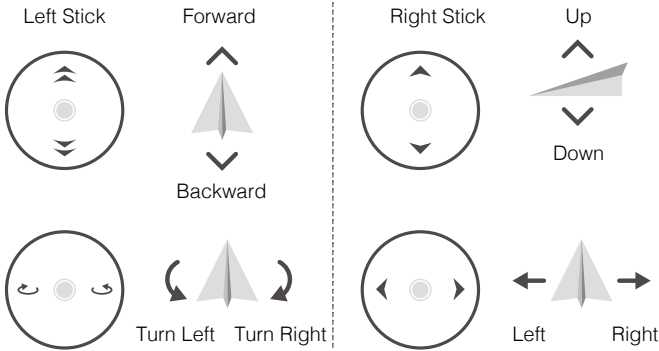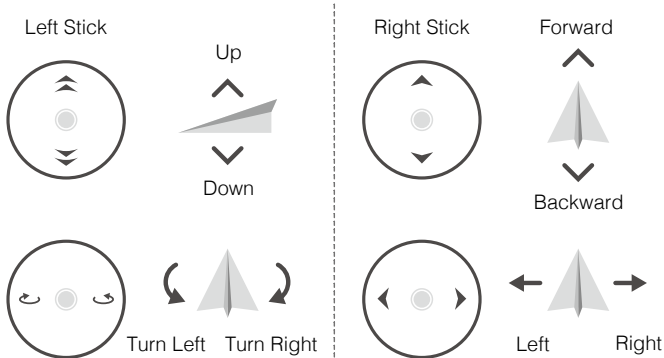
The figure below explains how to use each virtual joystick, using Mode 2 as an example.

Virtual Joysticks (Mode 2)	Remarks
Left Stick	Moving the left stick up or down changes the aircraft's altitude. Push the stick up to ascend and down to descend. The more the stick is pushed away from the center position, the faster the aircraft will change altitude. Always push the stick gently to prevent sudden and unexpected changes in altitude.

Left Stick	Moving the left stick to the left or right controls the orientation of the aircraft. Push the stick left to rotate the aircraft counter-clockwise and right to rotate the aircraft clockwise. The more the stick is pushed away from the center position, the faster the aircraft will rotate.
Right Stick	Moving the right stick up and down changes the aircraft's pitch. Push the stick up to fly forward and down to fly backward. The more the stick is pushed away from the center position, the faster the aircraft will move.
Right Stick	Moving the right stick to the left or right changes the aircraft's roll. Push the stick left to fly left and right to fly right. The more the stick is pushed away from the center position, the faster the aircraft will move.

⚠ • The area beyond the white circles is also responsive to control commands.
   • Tello is currently compatible with the customized Gamesir T1D. The virtual joysticks are disabled when connected to a remote controller via Bluetooth.

Program Platform

Besides the Tello EDU app, RoboMaster TT supports several computer programming software Click the links below to view manual documents and learn more about how to program.

Tello SDK 3.0
Mind+
Arduino

Firmware Updates

Updates Aircraft

When you connect the aircraft to the Tello app you will be notified if a new firmware update is available. To start updating, connect your mobile device to the Internet and follow the on-screen instructions.

⚠ • Firmware updates take around 5 minutes.
 • Before performing an update ensure the Flight Battery has at least 50% charge.

Updates Expansion Kit

Update the open-source controller firmware to the latest version using RoboMaster Assistant.
How to update firmware:
a. Download and install the DJI Education Hub at http://edu.dji.com/download.
b. Launch RoboMaster Assistant.
c. Connect the open-source controller to the computer using a micro USB cable. Follow the instructions to update firmware.

Flight

Ensure that all flights are carried out indoors or in an open area with no wind. The flight altitude is limited to 98.4 ft (30 m) and flight distance is limited to 328 ft (100 m). Perform a simple test flight the first time you fly the aircraft. Refer to the Test Flight section below.

Flight Environment Requirements

1. DO NOT use the aircraft in adverse weather conditions such as rain, snow, fog, wind, smog, hail, lightning, tornadoes, or hurricanes.
2. Only fly at locations where you can keep the aircraft at least 33 ft (10 m) away from obstacles, people, animals, buildings, public infrastructure, trees, and bodies of water when in flight.
3. DO NOT fly the aircraft on a route that has an abrupt change in the ground level (such as from inside a building to outside), otherwise the positioning function may be disrupted, impacting flight safety.
4. Aircraft and battery performance is subject to environmental factors such as air density and temperature. Be very careful when flying 3,281 ft (1,000 m) or more above sea level, since battery and aircraft performance may be reduced.

5. DO NOT use the aircraft near accidents, fire, explosions, floods, tsunamis, avalanches, landslides, earthquakes, dust, or sandstorms.
6. To avoid interference between your smart device and other wireless equipment, turn off other wireless equipment while you are flying the aircraft.
7. DO NOT fly in areas where magnetic or radio interference may occur such as close to: Wi-Fi hotspots, routers, Bluetooth devices, high voltage lines, high voltage power transmission stations, mobile base stations, or broadcasting towers. Flying in areas where interference may disrupt communication between the aircraft and the remote control device may adversely affect flight orientation and location accuracy and may potentially lead to loss of control. Interference may also lead to video downlink errors.

Compliance with Regulations

To avoid serious injury and property damage, observe local laws and regulations during flight. Refer to the *Tello Disclaimer and Safety Guidelines* for details.

Test Flight

Perform a simple test flight the first time you fly the aircraft:
1. Place the aircraft in a flat area with the Flight Battery facing towards you.
2. Turn on the aircraft.
3. Connect to the Wi-Fi named TELLO-xxxxxx or RMTT-xxxxxx, and then Launch the Tello app and enter the camera view.
4. Use auto takeoff.
5. Use the virtual joysticks to control the aircraft.
6. Use auto landing.
7. Turn off the aircraft.

Specifications

Tello (Model: TLW004)	
Weight (Propeller Guards Included)	87 g
Max Speed	17.8 mph (28.8 kph)
Max Flight Time	13 minutes (0 wind at a consistent 9 mph (15 kph))
Operating Temperature	32° to 104° F (0° to 40° C)
Operating Frequency	2.4 to 2.4835 GHz
Transmitter (EIRP)	<20 dBm (FCC) <19 dBm (CE) <19 dBm (SRRC)
Camera	
Max Image Size	2592×1936
Video Recording Modes	HD: 1280×720 30p
Video Format	MP4
Flight Battery	
Capacity	1100 mAh
Voltage	3.8 V

Battery Type	LiPo
Energy	4.18 Wh
Net Weight	25±2 g
Charging Temperature Range	41° to 113° F (5° to 45° C)
Max Charging Power	10 W
Expansion Kit	
Open-Source Controller	
Model	RMTTOC
Operating Mode	Direct Connection Mode, Router Mode
Wi-Fi	2.4 GHz , 5.8 GHz
Transmitter (EIRP)	2.4 GHz: <18.5dBm(FCC/SRRC/MIC); <17 dBm(CE) 5.8 GHz: <15 dBm(FCC/SRRC); <13 dBm(CE)
Bluetooth	2.4 GHz
MCU	ESP32-D2WD, Dual-Core Main Frequency: 160 MHz, Calculation ability: 400 MIPS
Open-Source	Supports SDK, Arduino, Scratch and MicroPython
Expansion	14-pin expansion port (I2C, UART, SPI, GPIO, PWM, power source)
LED	Full Color LED
Dot-Matrix Display & Distance Sensing Module	
Dot-Matrix LED	Red and blue LED 8×8
Dot-Matrix Driver function	IIC data port, auto dot-matrix scan, adjustable 256 global brightness, adjustable single-pixel red and blue LED 256 brightness
Distance Sensing Module	TOF
Maximum Sensing Distance of TOF	1.2 m (indoors with white wall)
Extension Board	
DIY Connection	14-pin extension port to 2×7 pin, 2.54mm dual in-line package, two reserved positions for 5V/3.3V power indicators, two reserved positions for test indicators

After-Sales Information

Visit https://www.dji.com/robomaster-tt to learn more about after-sales service policies, repair services and support.

This content is subject to change.

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https://www.dji.com/robomaster-tt