

# 13.56M RFID Reader QU-60x Serial

## Manual

(version 1.6)

ISO15693

- English

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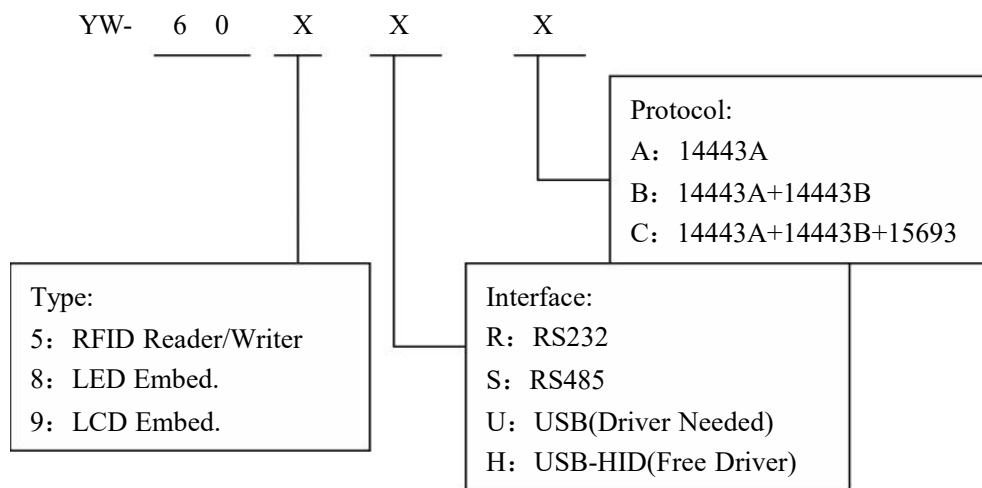
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# 1 Introduction

YW-605 RFID reader/Writer is the 13.56M HF tags Reader and Writer. She Can support ISO14443A, ISO14443B and ISO15693 RFID tags.

## 2 YW-605 Serial

13.56M RFIDReader/Writer



## 3 Feature

☞ Distance of read tags is 5-10cm

☞ DLL API supported. VC, VB, Delphi, C++Builder, C#.net, WEB example

☞ Beep and LED embed, which can be controlled by API.

## 4 Specifications

- ☞ Baud: 19200BPS
- ☞ Power: DC5V  $\pm$  10%
- ☞ Max Con: 1.5W
- ☞ Temp:  $-30^{\circ}\text{C} \sim +70^{\circ}\text{C}$
- ☞ Humidity: 35%  $\sim$  95%
- ☞ Size: 120 \* 84 \* 25 (mm)
- ☞ Weight: 100g

## 5 Program Manual

DLL API and functions

1. Get the version of DLL

**prototype:** `int stdcall YW_GetDLLVersion(void);`

**Param:** 无

**Return:** version Number is success, else is fail.

2. DES

**prototype:** `int stdcall DES(unsigned char cModel, unsigned char *pkey, unsigned char *in, unsigned char *out);`

**Param:**

Param	Type	

cModel	unsigned char	Direction: 0 Encryption, 1 Decryption
pkey	unsigned char*	Key , 8 Bytes
in	unsigned char*	Data ,8 bytes
out	unsigned char*	Data after Des, 8bytes

**Return:** 0

### 3. 3DES

**prototype:** `int stdcall DES3(unsigned char cModel, unsigned char *pKey, unsigned char *In, unsigned char *Out);`

**Param:**

Param	Type	
cModel	unsigned char	Direction: 0 Encryption, 1 Decryption
pkey	unsigned char*	Key, 16Bytes
in	unsigned char*	Data ,8 bytes
out	unsigned char*	Data after Des, 8bytes

**Return:** 0

### 4. 3DES with vector

**prototype:** `int stdcall DES3_CBC(unsigned char cModel, unsigned char`

\*pKey, unsigned char \*In, unsigned char \*Out, unsigned char \*pIV);

Param:

Param	Type	
cModel	unsigned char	Direction: 0 Encryption, 1 Decryption
pkey	unsigned char*	Key, 16Bytes
in	unsigned char*	Data ,8 bytes
out	unsigned char*	Data after Des, 8bytes
pIV	unsigned char*	Vector , 8Bytes

Return: 0

## 5. Initial Serial Port

prototype: `int` stdcall YW\_ComInitial(`int` PortIndex, `int` Bound);

Param:

Param	Type	
PortIndex	<code>int</code>	Port Number, 1--255
Bound	<code>int</code>	Baud, 2400—115200, 19200default

Return: 1 success, 0 fail

## 6. Free Serial port

prototype: `int` stdcall YW\_ComFree(void);

Param:

**Return:** 1 success, 0 fail

#### 7. Initial HID Port

**prototype:** `int stdcall YW_USBHIDInitial(void);`

**Param:**

**Return:** 1 success, 0 fail

#### 8. Free HID Port

**prototype:** `int stdcall YW_USBHIDFree(void);`

**Param:**

**Return:** 1 success, 0 fail

#### 9. Change the serial port baud

**prototype:** `int stdcall YW_ComNewBound(int ReaderID ,int NewBound);`

**Param:**

Param	Type	
ReaderID	<code>int</code>	Reader ID, default ID=0
NewBound	<code>int</code>	New Baud 0x01->9600bps 0x02->14400bps 0x03->19200bps 0x04->28800bps 0x05->38400bps 0x06->57600bps 0x07->115200bps

**Return:** 1 success, 0 fail

#### 10. Set Reader ID



**prototype:** `int` stdcall YW\_SetReaderID(`int` OldID, `int` NewID);

**Param:**

Param	Type	
OldID	<code>int</code>	Old Reader ID
NewID	<code>int</code>	New Read ID

**Return:** 1 success, 0 fail

#### 11. Get Reader ID

**prototype:** `int` stdcall YW\_GetReaderID(`int` ReaderID);

**Param:**

Param	Type	
ReaderID	<code>int</code>	ReaderID=0

**Return:**  $\geq 0$  success and is Reader ID, other is fail

#### 12. Get Reader Firmware version

**prototype:** `int` stdcall YW\_GetReaderVersion(`int` ReaderID);

**Param:**

Param	Type	
ReaderID	<code>int</code>	Reader ID

**Return:**  $\geq 0$  success and is version, other is fail

#### 13. Get Reader serial No.

**prototype:** `int` stdcall YW\_GetReaderSerial(`int` ReaderID, char \*ReaderSerial);

**Param:**

Param	Type	
ReaderID	<code>int</code>	Reader ID
ReaderSerial	Char *	Reader Serial, 8 Bytes

**Return:** 1 success, 0 fail

## 14. Beep control

**prototype:** `int` stdcall YW\_Buzzer(`int` ReaderID, `int` Time\_ON, `int` Time\_OFF, `int` Cycle);

**Param:**

Param	Type	
ReaderID	<code>int</code>	Reader ID
Time_ON	<code>int</code>	Beep on time, unit:100ms
Time_OFF	<code>int</code>	Beep off time, unit:100ms
Cycle	<code>int</code>	The weeks of the beep on and off

**Return:** 1 success, 0 fail

## 15. LED control

**prototype:** `int` stdcall YW\_Led(`int`ReaderID, `int`LEDIndex, `int`Time\_ON, `int` Time\_OFF, `int` Cycle, `int` LedIndexOn);

**Param:**

Param	Type	
ReaderID	<code>int</code>	Reader ID
LEDIndex	<code>int</code>	LED index 01: Read 02: Green 04: Yellow
Time_ON	<code>int</code>	LED On Time, unit:100ms
Time_OFF	<code>int</code>	LED Off Time, unit:100ms
Cycle	<code>int</code>	The weeks of the Led on and off
LedIndexOn	<code>int</code>	The index of Led on last: 00: all off 01: Read 02: Green

		04: Yellow
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**Return:** 1 success, 0 fail

#### 16. Set Content of 8 LED display

**prototype:** `int stdcall YW_LEDDisplay(int ReaderID, int Alignment, char *LEDText);`

**Param:**

Param	Type	
ReaderID	<code>int</code>	Reader ID
Alignment	<code>int</code>	Alignment 1: Left 2: Center 3: Right
LEDText	<code>Char *</code>	The string to be displayed The char can be below 0123456789AbCdEF.-

**Return:** 1 success, 0 fail

#### 17. Set the Status of Antenna

**prototype:** `int stdcall YW_AntennaStatus(int ReaderID, bool Status);`

**Param:**

Param	Type	
ReaderID	<code>int</code>	Reader ID
Status	<code>bool</code>	True: Open RF Antenna False: Close RF Antenna

**Return:** 1 success, 0 fail

#### 18. Set Work Mode of Tags

**prototype:** `int stdcall YW_SearchCardMode(int ReaderID, int SearchMode);`

**Param:**

Param	Type	
ReaderID	<code>int</code>	Reader ID
SearchMode	<code>char</code>	Tags 0x41-----IS014443A 0x42----- IS014443B 0x31----- IS015693 0x53-----ST Serail 0x52-----AT88RF020

**Return:** 1 success, 0 fail

Functions about Tags of IS015693

19. 15693 Tags Inventory

**prototype:** `int stdcall YW_IS015693_Inventory(int ReaderID, unsigned char *PData, unsigned char *PLen);`

**Param:**

Param	Type	
ReaderID	<code>int</code>	Reader ID
PData	<code>unsigned char *</code>	If Succes, Flag(1byte)+ UID(8Byte)
PLen	<code>unsigned char *</code>	Length of PData

**Return:** 1 success, 0 fail

20. 15693 Tags Stay\_Quiet

**prototype:** `int stdcall YW_IS015693_Stay_Quiet(int ReaderID, unsigned char *PUIID);`

**Param:**

Param	Type	
ReaderID	int	Reader ID
PUID	unsigned char *	UID(8Byte) of Tags

**Return:** 1 success, 0 fail

## 21. Select Tag of IS015693

**prototype:** int stdcall YW\_IS015693\_Select(int ReaderID, unsigned char Model, unsigned char \*PUID);

**Param:**

Param	Type	
ReaderID	int	Reader ID
Model	unsigned char	Model=0x00 Select Tag With Flag Model=0x02 Select Tag with UID
PUID	unsigned char *	UID(8Byte) of Tags

**Return:** 1 success, 0 fail

## 22. Reset To Ready of IS015693 Tag

**prototype:** int stdcall YW\_IS015693\_Reset\_To\_Ready(int ReaderID, unsigned char Model, unsigned char \*PUID);

**Param:**

Param	Type	
ReaderID	int	Reader ID
Model	unsigned char	Model=0x00 Select Tag With Flag

		Model=0x02 Select Tag with UID
PUID	unsigned char *	UID(8Byte) of Tags

**Return:** 1 success, 0 fail

### 23. Read Block of IS015693 Tag

**prototype:** int stdcall YW\_IS015693\_Read(int ReaderID, unsigned char Model, unsigned char \*PUID, unsigned char StartBlockID, unsigned char BlockNums, unsigned char \*PData, unsigned char \*PLen);

**Param:**

Param	Type	
ReaderID	int	Reader ID
Model	unsigned char	Model=0x00 Select Tag With Flag Model=0x02 Select Tag with UID
PUID	unsigned char *	UID(8Byte) of Tags
StartBlockID	unsigned char	Block ID Begin
BlockNums	unsigned char	Numbers of Blocks
PData	unsigned char *	Data read
PLen	unsigned char *	Lenth of PData

**Return:** 1 success, 0 fail

## 24. Write Block of IS015693 Tag

**prototype:** `int stdcall YW_IS015693_Write(int ReaderID, unsigned char Model, unsigned char *PUID, unsigned char BlockID, unsigned char DataLen, unsigned char *PData);`

**Param:**

Param	Type	
ReaderID	<code>int</code>	Reader ID
Model	<code>unsigned char</code>	This value depends on the card . Bit0=1 Select Tag With Flag Bit1=1 Select Tag with UID Bit2=1 depends on the Tags
PUID	<code>unsigned char *</code>	UID(8Byte) of Tags
BlockID	<code>unsigned char</code>	Block ID Begin
DataLen	<code>int</code>	Length of PData
PData	<code>unsigned char *</code>	Data will be written

**Return:** 1 success, 0 fail

## 25. Lock Block of IS015693 Tags

**prototype:** `int stdcall YW_IS015693_Lock_Block(int ReaderID, unsigned char Model, unsigned char *PUID, unsigned char BlockID);`

**Param:**

Param	Type	
ReaderID	<code>int</code>	Reader ID
Model	<code>unsigned char</code>	This value depends on the card .

		Bit0=1 Select Tag With Flag Bit1=1 Select Tag with UID Bit2=1 depends on the Tags
PUID	unsigned char *	UID(8Byte) of Tags
BlockID	unsigned char	The block ID

**Return:** 1 success, 0 fail

26. Write AFI of ISO15693 Tags

**prototype:** `int stdcall YW_ISO15693_Write_AFI(int ReaderID, unsigned char Model, unsigned char *PUID, unsigned char AFI);`

**Param:**

Param	Type	
ReaderID	int	Reader ID
Model	unsigned char	This value depends on the card . Bit0=1 Select Tag With Flag Bit1=1 Select Tag with UID Bit2=1 depends on the Tags
PUID	unsigned char *	UID(8Byte) of Tags
AFI	unsigned char	AFI Value

**Return:** 1 success, 0 fail

27. Lock AFI of ISO15693 Tags



**prototype:** `int stdcall YW_IS015693_Lock_AFI (int ReaderID, unsigned char Model, unsigned char *PUID);`

**Param:**

Param	Type	
ReaderID	<code>int</code>	Reader ID
Model	<code>unsigned char</code>	This value depends on the card . Bit0=1 Select Tag With Flag Bit1=1 Select Tag with UID Bit2=1 depends on the Tags
PUID	<code>unsigned char *</code>	UID(8Byte) of Tags

**Return:** 1 success, 0 fail

28. Write DSFIC of IS015693 Tags

**prototype:** `int stdcall YW_IS015693_Write_DSFI (int ReaderID, unsigned char Model, unsigned char *PUID, unsigned char DSFI);`

**Param:**

Param	Type	
ReaderID	<code>int</code>	Reader ID
Model	<code>unsigned char</code>	This value depends on the card . Bit0=1 Select Tag With Flag Bit1=1 Select Tag with UID Bit2=1 depends on the Tags
PUID	<code>unsigned char *</code>	UID(8Byte) of Tags
DSFI	<code>unsigned</code>	DSFI Value

	char	
--	------	--

**Return:** 1 success, 0 fail

### 29. Lock DSFIC of ISO15693 Tags

**prototype:** `int stdcall YW_ISO15693_Lock_DSFIID(int ReaderID, unsigned char Model, unsigned char *PUIID);`

**Param:**

Param	Type	
ReaderID	int	Reader ID
Model	unsigned char	This value depends on the card . Bit0=1 Select Tag With Flag Bit1=1 Select Tag with UID Bit2=1 depends on the Tags
PUIID	unsigned char *	UID(8Byte) of Tags

**Return:** 1 success, 0 fail

### 30. Get System Information of ISO15693 Tags

**prototype:** `int stdcall YW_ISO15693_Get_System_Information(int ReaderID, unsigned char Model, unsigned char *PUIID, unsigned char *PData, unsigned char *PLen);`

**Param:**

Param	Type	
ReaderID	int	Reader ID
Model	unsigned char	Model=0x00 Select Tag With Flag Model=0x02 Select Tag with

		UID
PUID	unsigned char *	UID(8Byte) of Tags
PData	unsigned char *	System Infomation
PLen	unsigned char *	Length of System Infomation

**Return:** 1 success, 0 fail

### 31. Get Security of Blocks about ISO15693 Tag

**prototype:** `int stdcall YW_ISO15693_Get_Block_Security(int ReaderID, unsigned char Model, unsigned char *PUID, unsigned char StartBlockID, unsigned char BlockNums, unsigned char *PData, unsigned char *PLen);`

**Param:**

Param	Type	
ReaderID	int	Reader ID
Model	unsigned char	Model=0x00 Select Tag With Flag Model=0x02 Select Tag with UID
PUID	unsigned char *	UID(8Byte) of Tags
StartBlockID	unsigned char	Block ID Begin
BlockNums	unsigned char	Number of Blocks
PData	unsigned char *	Security Infomation
PLen	unsigned	Length of Security

	<code>char *</code>	Information
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**Return:** 1 success, 0 fail

### 32. Multi Inventory of ISO15693 Tags

**prototype:** `int stdcall YW_ISO15693_Multi_Inventory(int ReaderID, unsigned char AFIEEnable, unsigned char AFI, unsigned char *PData, unsigned char *PLen);`

**Param:**

Param	Type	
ReaderID	<code>int</code>	Reader ID
AFIEEnable	<code>unsigned char</code>	0
AFI	<code>unsigned char</code>	0
PData	<code>unsigned char *</code>	UIDs of many Tags
PLen	<code>unsigned char *</code>	Length of UIDs

**Return:** 1 success, 0 fail

### Functions of SAM

#### 33. SAM Baud

**prototype:** `int __stdcall YW_SAM_ResetBaud(int ReaderID, int SAMIndex, int BaudIndex);`

**Param:**

Param	Type	
ReaderID	<code>int</code>	Reader ID
SAMIndex	<code>int</code>	SAM Index
BaudIndex	<code>int</code>	0x00-→9600 (Default)

		0x01→19200
		0x02→38400
		0x03→55800
		0x04→57600
		0x05→115200

**Return:** 1 success, 0 fail

#### 34. SAM Reset

**prototype:** `int __stdcall YW_SAM_Reset(int ReaderID, int SAMIndex, int *rtLen, unsigned char *pData);`

**Param:**

Param	Type	
ReaderID	<code>int</code>	Reader ID
SAMIndex	<code>int</code>	SAM Index
rtLen	<code>int *</code>	Length of PData
pData	<code>unsigned char *</code>	Data return of Sam Reset

**Return:** 1 success, 0 fail

#### 35. Excute COS Command of SAM

**prototype:** `int __stdcall YW_SAM_COS(int ReaderID, int SAMIndex, int LenCOS, unsigned char *Com_COS, int *rtLen, unsigned char *pData);`

**Param:**

Param	Type	
ReaderID	<code>int</code>	Reader ID
SAMIndex	<code>int</code>	SAM Index
LenCOS	<code>int</code>	Length of COS Command
Com_COS	<code>unsigned char *</code>	COS Command

rtLen	unsigned char *	Length of pData
pData	unsigned char *	Data return after execution of COS Command

**Return:** 1 success, 0 fail

### 36. SAM PPS Baud

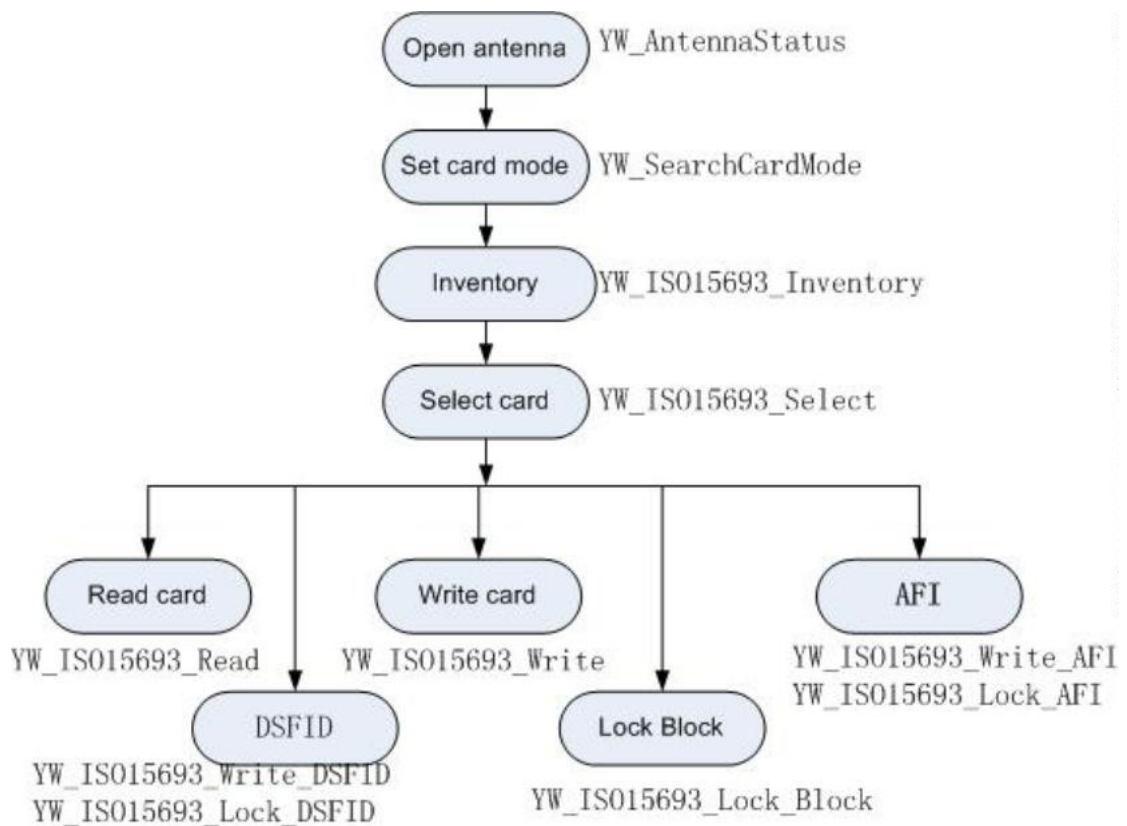
**prototype:** int \_\_stdcall YW\_SAM\_PPSBaud(int ReaderID, int SAMIndex, int BaudIndex);

**Param:**

Param	Type	
ReaderID	int	Reader ID
SAMIndex	int	SAM Index
BaudIndex	int	0x00->9600 (Default) 0x01->19200 0x02->38400 0x03->55800 0x04->57600 0x05->115200

**Return:** 1 success, 0 fail

## 6 ISO15693 card operation



## 7 Order Information

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