

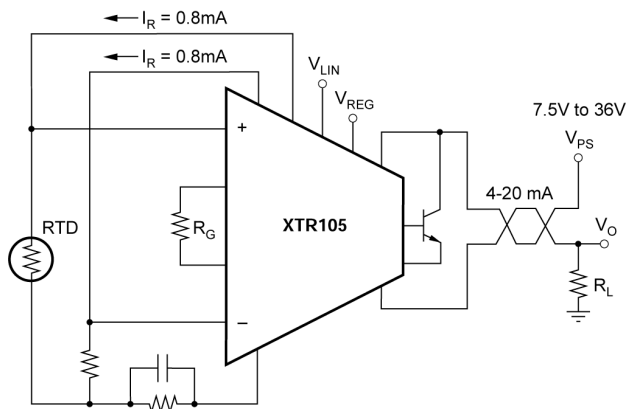
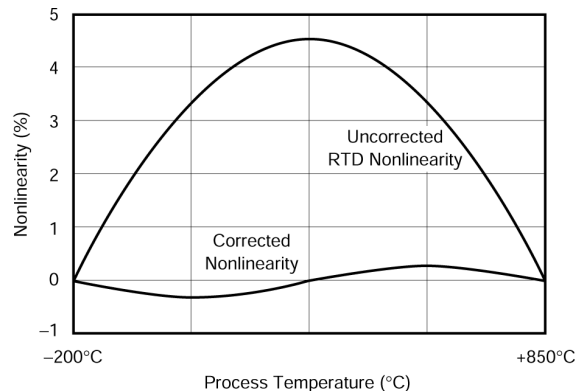
# XTR105 4-20mA Current Transmitter With Sensor Excitation and Linearization

## 1 Features

- Low unadjusted error
- Two precision current sources: 800 $\mu$ A each
- Linearization
- 2-wire or 3-wire RTD operation
- Low offset drift: 0.4 $\mu$ V/ $^{\circ}$ C
- Low output current noise: 30nA<sub>PP</sub>
- High PSR: 110dB minimum
- High CMR: 86dB minimum
- Wide supply range: 7.5V to 36V
- Packages: DIP-14 and SO-14

## 2 Applications

- [Field transmitter and sensor](#)
- [Factory automation](#)
- [Compatible with HART modem](#)
- Temperature and pressure transducers
- Industrial process control
- SCADA remote data acquisition
- 2-wire, 4-20mA current loop
- Voltage-to-current amplifier



**Pt100 Nonlinearity Correction Using the XTR105**

## 3 Description

The XTR105 is a monolithic 4mA-to-20mA, 2-wire current transmitter with two precision current sources. This device provides complete current excitation for platinum RTD temperature sensors and bridges, instrumentation amplifiers, and current output circuitry on a single integrated circuit.

Versatile linearization circuitry provides a 2nd-order correction to the RTD, typically achieving a 40:1 improvement in linearity.

Instrumentation amplifier gain can be configured for a wide range of temperature or pressure measurements. Total unadjusted error of the complete current transmitter is low enough to permit use without adjustment in many applications. This includes zero output current drift, span drift, and nonlinearity. The XTR105 operates on loop power-supply voltages down to 7.5V.

The XTR105 is available in DIP-14 and SO-14 surface-mount packages and is specified for the industrial temperature range of  $-40^{\circ}\text{C}$  to  $+85^{\circ}\text{C}$ .

### Package Information

PART NUMBER	PACKAGE <sup>(1)</sup>	PACKAGE SIZE <sup>(2)</sup>
XTR105	D (SOIC, 14)	8.65mm × 6mm
	N (PDIP, 14)	19.3mm × 9.4mm

(1) For more information, see [Section 10](#).

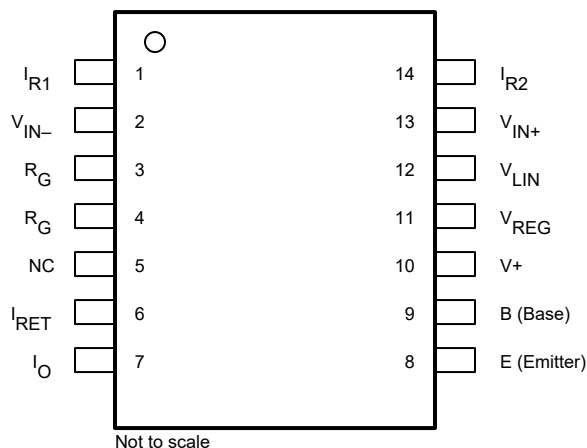
(2) The package size (length × width) is a nominal value and includes pins, where applicable



## Table of Contents

<b>1 Features</b> .....	<b>1</b>	<b>7 Application and Implementation</b> .....	<b>15</b>
<b>2 Applications</b> .....	<b>1</b>	7.1 Application Information.....	15
<b>3 Description</b> .....	<b>1</b>	7.2 Typical Applications.....	22
<b>4 Pin Configuration and Functions</b> .....	<b>3</b>	7.3 Layout.....	23
<b>5 Specifications</b> .....	<b>4</b>	<b>8 Device and Documentation Support</b> .....	<b>24</b>
5.1 Absolute Maximum Ratings <sup>(1)</sup> .....	4	8.1 Documentation Support.....	24
5.2 Recommended Operating Conditions.....	4	8.2 Receiving Notification of Documentation Updates....	24
5.3 Thermal Information.....	4	8.3 Support Resources.....	24
5.4 Electrical Characteristics.....	5	8.4 Trademarks.....	24
5.5 Typical Characteristics.....	7	8.5 Electrostatic Discharge Caution.....	24
<b>6 Detailed Description</b> .....	<b>10</b>	8.6 Glossary.....	24
6.1 Overview.....	10	<b>9 Revision History</b> .....	<b>24</b>
6.2 Functional Block Diagram.....	11	<b>10 Mechanical, Packaging, and Orderable Information</b> .....	<b>25</b>
6.3 Feature Description.....	11		
6.4 Device Functional Modes.....	14		

## 4 Pin Configuration and Functions



**Figure 4-1. D Package, 14-Pin SOIC, and N Package, 14-Pin PDIP (Top View)**

**Table 4-1. Pin Functions**

PIN		TYPE	DESCRIPTION
NAME	NO.		
B (Base)	9	Output	Base connection for external transistor
E (Emitter)	8	Input	Emitter connection for external transistor
I <sub>O</sub>	7	Output	Regulated 4mA to 20mA current loop output
I <sub>R1</sub>	1	Output	800μA reference current output, channel 1
I <sub>R2</sub>	14	Output	800μA reference current output, channel 2
I <sub>RET</sub>	6	Input	<i>Local ground</i> return pin for V <sub>REG</sub> , V <sub>LIN</sub> , I <sub>R1</sub> , and I <sub>R2</sub>
NC	5	—	Not internally connected
R <sub>G</sub>	3, 4	—	Input stage gain setting pins. The resistance R <sub>G</sub> between pins 3 and 4 sets the gain of the voltage-to-current transfer function
V+	10	Power	Loop power supply
V <sub>IN-</sub>	2	Input	Negative (inverting) differential voltage input
V <sub>IN+</sub>	13	Input	Positive (noninverting) differential voltage input
V <sub>LIN</sub>	12	Output	Linearity correction voltage output
V <sub>REG</sub>	11	Output	5.1V regulator voltage output

## 5 Specifications

### 5.1 Absolute Maximum Ratings <sup>(1)</sup>

		MIN	MAX	UNIT
V+	Power supply (referenced to the I <sub>O</sub> pin)		40	V
V <sub>IN</sub>	Input voltage, V <sub>IN+</sub> – V <sub>IN–</sub> (referenced to the I <sub>O</sub> pin)	0	V+	V
	Output current limit		Continuous	
T <sub>A</sub>	Operating temperature	–40	125	°C
T <sub>J</sub>	Junction temperature		165	°C
T <sub>stg</sub>	Storage temperature	–55	125	°C
	Lead temperature (soldering, 10s)		300	°C

- (1) Operation outside the *Absolute Maximum Ratings* may cause permanent device damage. *Absolute Maximum Ratings* do not imply functional operation of the device at these or any other conditions beyond those listed under *Recommended Operating Conditions*. If used outside the *Recommended Operating Conditions* but within the *Absolute Maximum Ratings*, the device may not be fully functional, and this may affect device reliability, functionality, performance, and shorten the device lifetime.

### 5.2 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

		MIN	NOM	MAX	UNIT
V+	Power supply (referenced to the I <sub>O</sub> pin)	7.5	24	36	V
T <sub>A</sub>	Specified temperature	–40		85	°C

### 5.3 Thermal Information

THERMAL METRICS <sup>(1)</sup>		XTR105		UNIT
		D (SOIC)	N (PDIP)	
		14 PINS		
R <sub>θJA</sub>	Junction-to-ambient thermal resistance	87.3	54.4	°C/W
R <sub>θJC(top)</sub>	Junction-to-case (top) thermal resistance	47.3	31.4	°C/W
R <sub>θJB</sub>	Junction-to-board thermal resistance	46.6	25.8	°C/W
Ψ <sub>JT</sub>	Junction-to-top characterization parameter	9.9	9.6	°C/W
Ψ <sub>JB</sub>	Junction-to-board characterization parameter	46.1	25.3	°C/W
R <sub>θJC(bot)</sub>	Junction-to-case (bottom) thermal resistance	N/A	N/A	°C/W

- (1) For more information about traditional and new thermal metrics, see the [Semiconductor and IC package thermal metrics](#) application note.

## 5.4 Electrical Characteristics

at  $T_A = +25^\circ\text{C}$ ,  $V_+ = 24\text{V}$ , and TIP29C external transistor (unless otherwise noted)

PARAMETER	TEST CONDITIONS		MIN	TYP	MAX	UNITS
OUTPUT						
Output current equation	V <sub>IN</sub> in volts, R <sub>G</sub> in ohms		I <sub>O</sub> = V <sub>IN</sub> × (40 / R <sub>G</sub> ) + 4mA			
Output current, specified range			4		20	mA
Overscale limit			24	27	30	mA
Underscale limit	I <sub>REG</sub> = 0V		1.8	2.2	2.6	mA
ZERO OUTPUT <sup>(1)</sup>	V <sub>IN</sub> = 0V, R <sub>G</sub> = ∞			4		mA
Initial error	XTR105P, XTR105U			±5	±25	µA
	XTR105PA, XTR105UA			±5	±50	
vs temperature	T <sub>A</sub> = −40 °C to +85°C	XTR105P, XTR105U		±0.07	±0.5	µA/°C
		XTR105PA, XTR105UA		±0.07	±0.9	
vs supply voltage, V+	V+ = 7.5V to 36V			0.04	0.2	µA/V
vs common-mode voltage	V <sub>CM</sub> = 1.25V to 3.5V <sup>(2)</sup>			0.02		µA/V
vs V <sub>REG</sub> output current				0.3		µA/mA
Noise, 0.1Hz to 10Hz				0.03		µA <sub>PP</sub>
SPAN						
Span equation (transconductance)				S = 40/R <sub>G</sub>		A/V
Initial error <sup>(3)</sup>	Full-scale (V <sub>IN</sub> ) = 50mV	XTR105P, XTR105U		±0.05	±0.2	%
		XTR105PA, XTR105UA		±0.05	±0.4	
vs temperature <sup>(3)</sup>	T <sub>A</sub> = −40 °C to +85°C			±3	±25	ppm/°C
Nonlinearity, ideal input <sup>(4)</sup>	Full-scale (V <sub>IN</sub> ) = 50mV			0.003	0.01	%
INPUT <sup>(5)</sup>						
Offset voltage	V <sub>CM</sub> = 2V	XTR105P, XTR105U		±50	±100	µV
		XTR105PA, XTR105UA		±50	±250	
vs temperature	T <sub>A</sub> = −40 °C to +85°C	XTR105P, XTR105U		±0.4	±1.5	µV/°C
		XTR105PA, XTR105UA		±0.4	±3	
vs supply voltage, V+	V+ = 7.5V to 36V			±0.3	±3	µV/V
vs common-mode voltage, RTI (CMRR)	V <sub>CM</sub> = 1.25V to 3.5V <sup>(2)</sup>	XTR105P, XTR105U		±10	±50	µV/V
		XTR105PA, XTR105UA		±10	±100	
Common-mode input range <sup>(2)</sup>			1.25		3.5	V
Input bias current	XTR105P, XTR105U			5	25	nA
	XTR105PA, XTR105UA			5	50	
vs temperature	T <sub>A</sub> = −40 °C to +85°C			20		pA/°C
Input offset current	XTR105P, XTR105U			±0.2	±3	nA
	XTR105PA, XTR105UA			±0.2	±10	
vs temperature	T <sub>A</sub> = −40 °C to +85°C			5		pA/°C
Impedance, differential				0.1    1		GΩ    pF
Common-mode				5    10		GΩ    pF
Noise, 0.1Hz to 10Hz				0.6		µA <sub>PP</sub>

**XTR105**

SBOS061C – FEBRUARY 1997 – REVISED OCTOBER 2024

## 5.4 Electrical Characteristics (continued)

at  $T_A = +25^{\circ}\text{C}$ ,  $V_+ = 24\text{V}$ , and TIP29C external transistor (unless otherwise noted)

PARAMETER	TEST CONDITIONS		MIN	TYP	MAX	UNITS
CURRENT SOURCES <sup>(6)</sup>						
Current				800		μA
Accuracy	XTR105P, XTR105U			±0.05	±0.2	%
	XTR105PA, XTR105UA			±0.05	±0.4	
vs temperature	T <sub>A</sub> = −40 °C to +85°C	XTR105P, XTR105U		±15	±35	ppm/°C
		XTR105PA, XTR105UA		±15	±75	
vs power supply, V+	V+ = 7.5V to 36V			±10	±25	ppm/V
Matching	XTR105P, XTR105U			±0.02	±0.1	%
	XTR105PA, XTR105UA			±0.02	±0.2	
vs temperature	T <sub>A</sub> = −40 °C to +85°C	XTR105P, XTR105U		±3	±15	ppm/°C
		XTR105PA, XTR105UA		±3	±30	
vs power supply, V+	V+ = 7.5V to 36V			1	10	ppm/V
Compliance voltage	Positive		(V+) − 3	(V+) − 2.5		V
	Negative <sup>(2)</sup>		0	−0.2		
Output impedance				150		MΩ
Noise, 0.1Hz to 10Hz				0.003		μA <sub>PP</sub>
V <sub>REG</sub> <sup>(2)</sup>				5.1		V
Accuracy				±0.02	±0.1	V
vs temperature	T <sub>A</sub> = −40 °C to +85°C			±0.5		mV/°C
vs supply voltage, V+				1		mV/V
Output current				±1		mA
Output impedance				75		Ω
LINEARIZATION						
R <sub>LIN</sub> (internal)				1		kΩ
Accuracy	XTR105P, XTR105U			±0.2	±0.5	%
	XTR105PA, XTR105UA			±0.2	±1	
vs temperature	T <sub>A</sub> = −40 °C to +85°C			±25	±100	ppm/°C

(1) Describes accuracy of the 4mA low-scale offset current. Does not include input amplifier effects. Can be trimmed to zero.

(2) Voltage measured with respect to  $I_{\text{RET}}$  pin.

(3) Does not include initial error or TCR of gain-setting resistor,  $R_G$ .

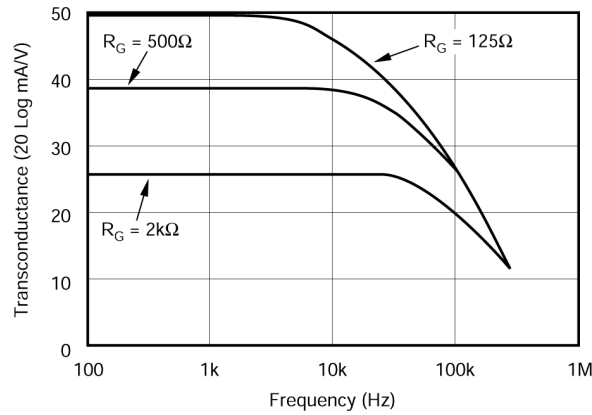
(4) Increasing the full-scale input range improves nonlinearity.

(5) Does not include zero output initial error.

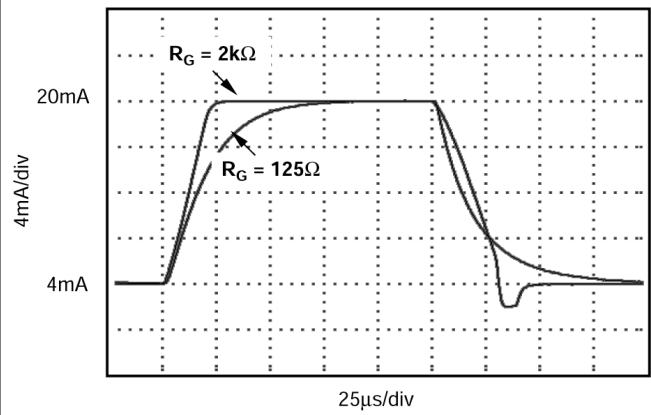
(6) Current source output voltage  $V_O = 2\text{V}$ , with respect to  $I_{\text{RET}}$  pin.

## 5.5 Typical Characteristics

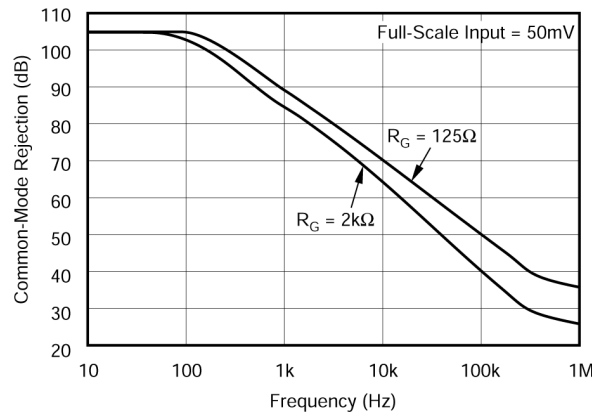
at  $T_A = +25^\circ\text{C}$  and  $V_+ = 24\text{V}$  (unless otherwise noted)



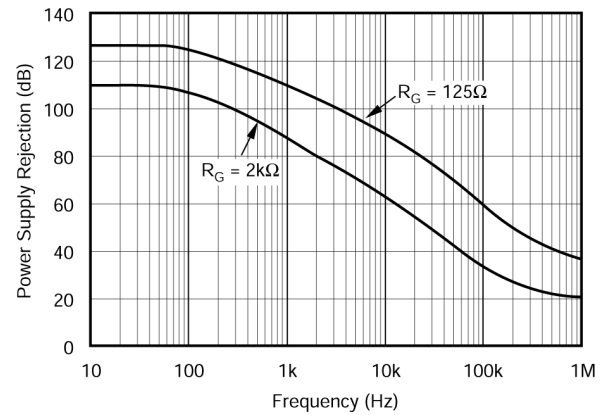
**Figure 5-1. Transconductance vs Frequency**



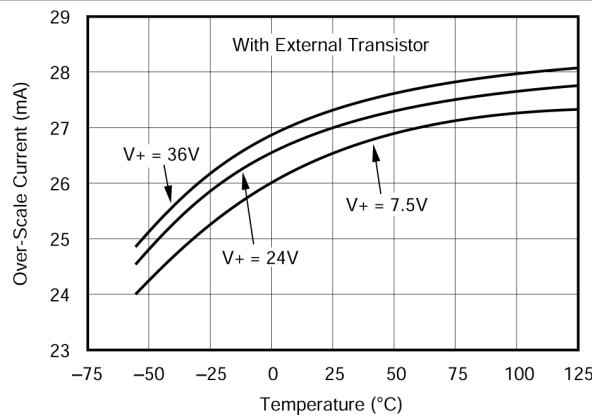
**Figure 5-2. Step Response**



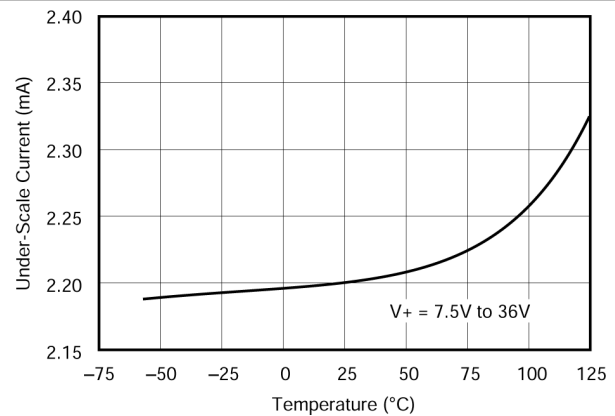
**Figure 5-3. Common-Mode Rejection vs Frequency**



**Figure 5-4. Power-Supply Rejection vs Frequency**



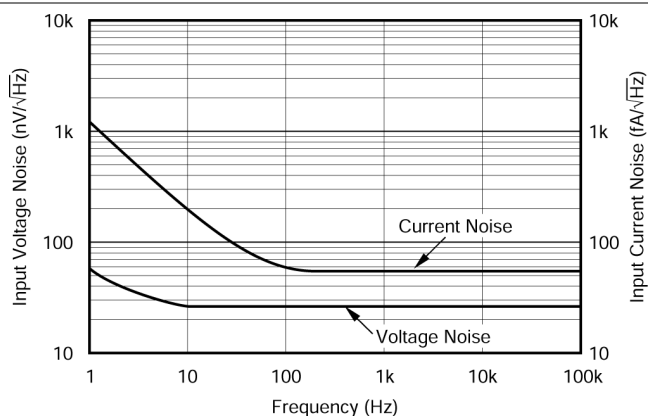
**Figure 5-5. Overscale Current vs Temperature**



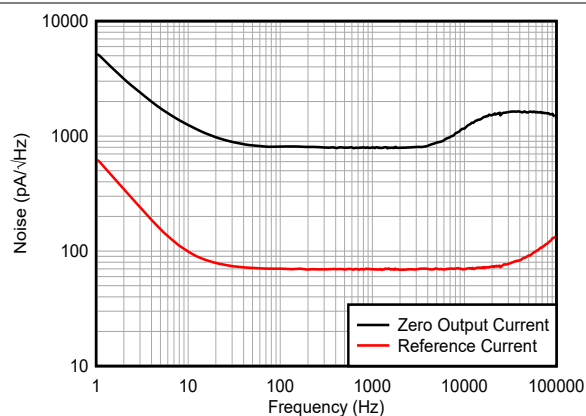
**Figure 5-6. Underscale Current vs Temperature**

## 5.5 Typical Characteristics (continued)

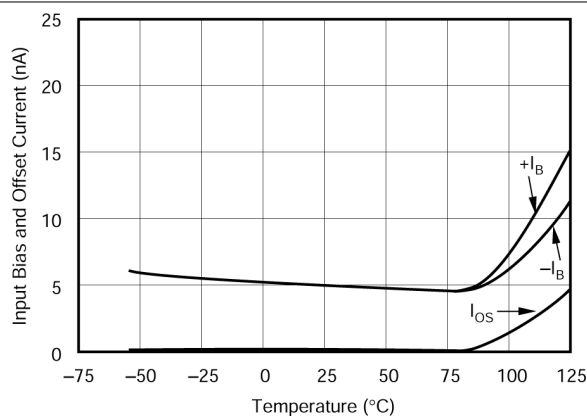
at  $T_A = +25^\circ\text{C}$  and  $V_+ = 24\text{V}$  (unless otherwise noted)



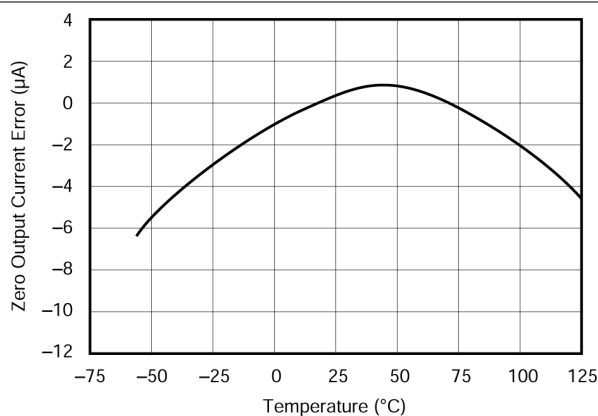
**Figure 5-7. Input Voltage and Current Noise Density vs Frequency**



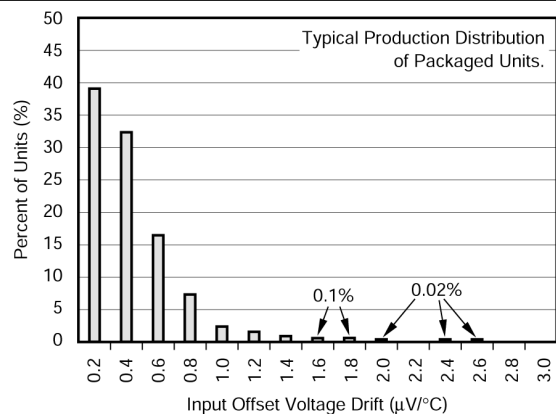
**Figure 5-8. Zero Output and Reference Current Noise vs Frequency**



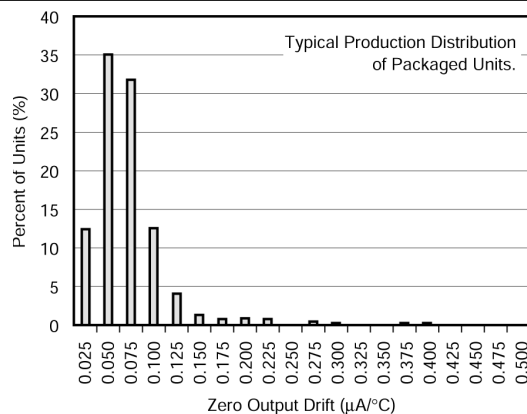
**Figure 5-9. Input Bias and Offset Current vs Temperature**



**Figure 5-10. Zero Output Current Error vs Temperature**



**Figure 5-11. Input Offset Voltage Drift Production Distribution**

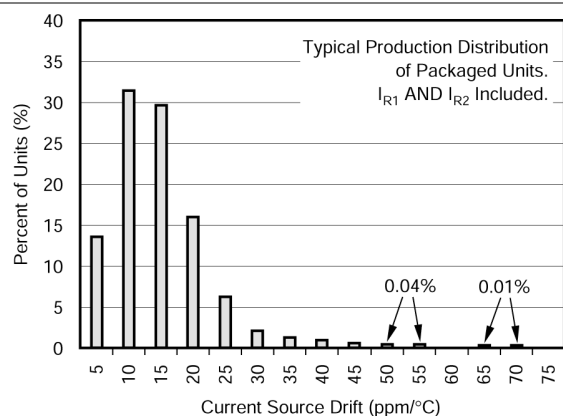


**Figure 5-12. Zero Output Drift Production Distribution**

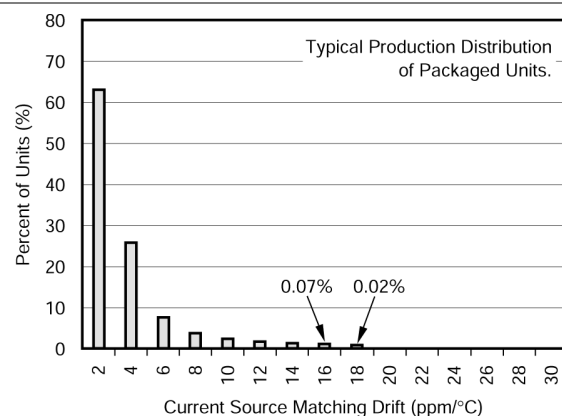


## 5.5 Typical Characteristics (continued)

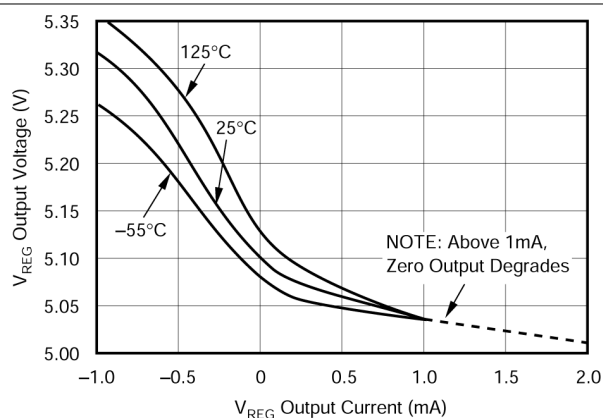
at  $T_A = +25^\circ\text{C}$  and  $V_+ = 24\text{V}$  (unless otherwise noted)



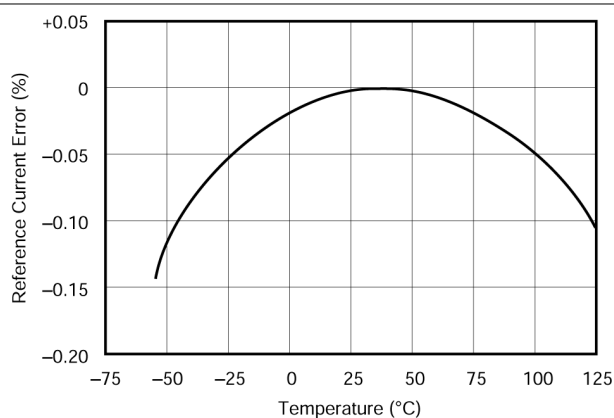
**Figure 5-13. Current Source Drift Production Distribution**



**Figure 5-14. Current Source Matching Drift Production Distribution**



**Figure 5-15.  $V_{REG}$  Output Voltage vs  $v_{REG}$  Output Current**



**Figure 5-16. Reference Current Error vs Temperature**

## 6 Detailed Description

### 6.1 Overview

The XTR105 is a monolithic 4mA-to-20mA, 2-wire current transmitter with a differential voltage input. Figure 6-1 shows the simplified schematic of the XTR105. The loop power supply,  $V_+$ , provides power for all circuitry. The output loop current is modulated by the XTR105 and is typically measured as a voltage across a series load resistor ( $R_L$ ).

The instrumentation amplifier input of the XTR105 measures the voltage difference between the noninverting and inverting inputs. This difference is then gained up according to the value of  $R_G$ , and expressed as a regulated current output.

The two matched 0.8mA current sources are typically used to drive an RTD and zero-setting resistor ( $R_Z$ ).  $R_Z$  determines the static offset of the current output and can be adjusted to correct for offset errors. A linearity correction feature is provided to further improve the RTD response. An additional 5.1V voltage regulator output is provided to power external circuitry such as buffer amplifiers.

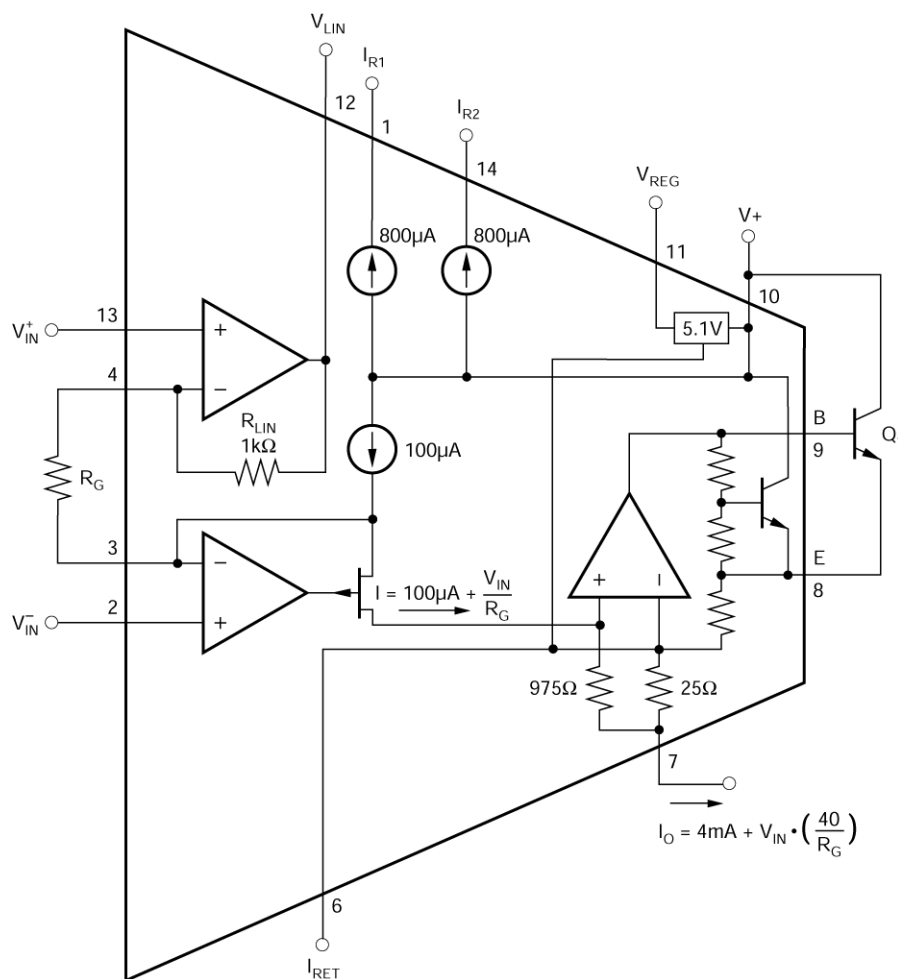
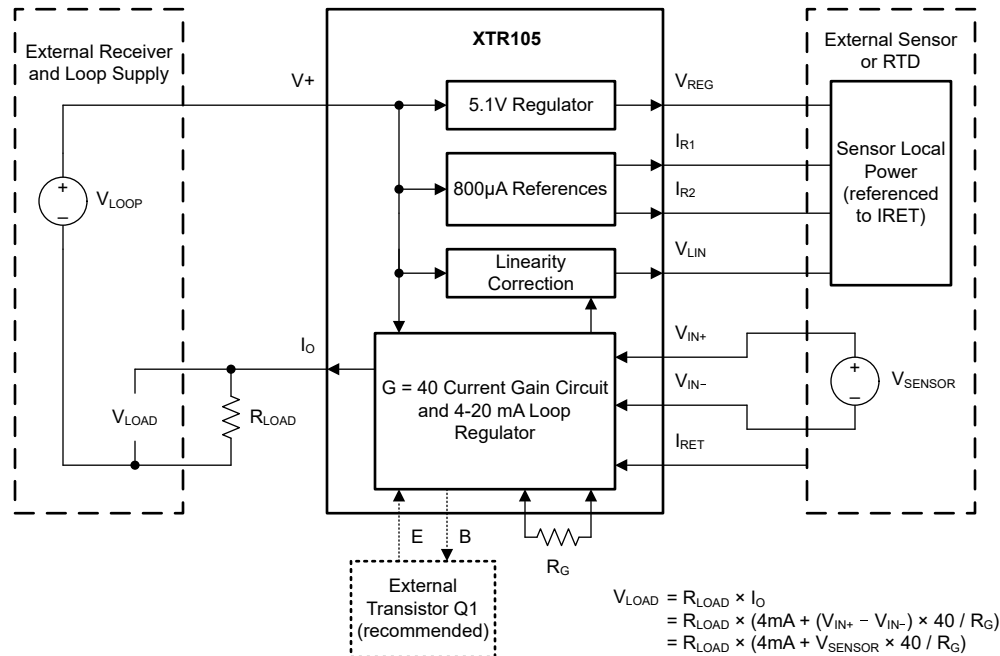


Figure 6-1. Simplified Schematic

## 6.2 Functional Block Diagram



## 6.3 Feature Description

### 6.3.1 Linearization

RTD temperature sensors are inherently (but predictably) nonlinear. With the addition of one or two external resistors,  $R_{LIN1}$  and  $R_{LIN2}$ , compensation is possible for most of this nonlinearity by using the  $V_{LIN}$  linearity correction feature of the XTR105. This results in a 40:1 improvement in linearity over the uncompensated output.

See Figure 7-1 for a typical 2-wire RTD application with linearization. Resistor  $R_{LIN1}$  provides positive feedback and controls linearity correction.  $R_{LIN1}$  is chosen according to the desired temperature range. An equation is given in Figure 7-1.

In 3-wire RTD connections, an additional resistor,  $R_{LIN2}$ , is required. As with the 2-wire RTD application,  $R_{LIN1}$  provides positive feedback for linearization.  $R_{LIN2}$  provides an offset canceling current to compensate for wiring resistance encountered in remotely located RTDs.  $R_{LIN1}$  and  $R_{LIN2}$  are chosen such that the currents are equal. This makes the voltage drop in the wiring resistance to the RTD a common-mode signal that is rejected by the XTR105. The nearest standard 1% resistor values for  $R_{LIN1}$  and  $R_{LIN2}$  are adequate for most applications. Table 7-1 provides the 1% resistor values for a 3-wire Pt100 RTD connection.

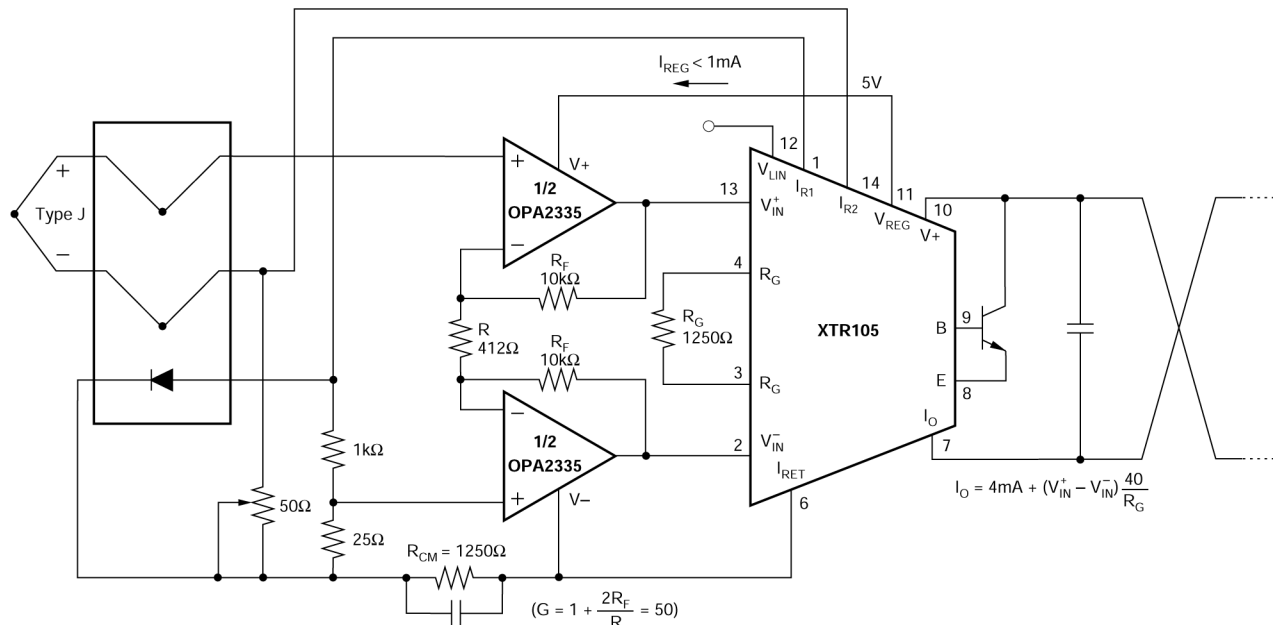
If no linearity correction is desired, leave the  $V_{LIN}$  pin open. With no linearization,  $R_G = 2500m \times V_{FS}$ , where  $V_{FS}$  = full-scale input range.

#### 6.3.1.1 High-Resistance RTDs

The text and figures thus far have assumed a Pt100 RTD. With higher resistance RTDs, evaluate the temperature range and input voltage variation to maintain proper common-mode biasing of the inputs. As mentioned previously,  $R_{CM}$  can be adjusted to provide an additional voltage drop to bias the inputs of the XTR105 within the common-mode input range.

### 6.3.2 Voltage Regulator

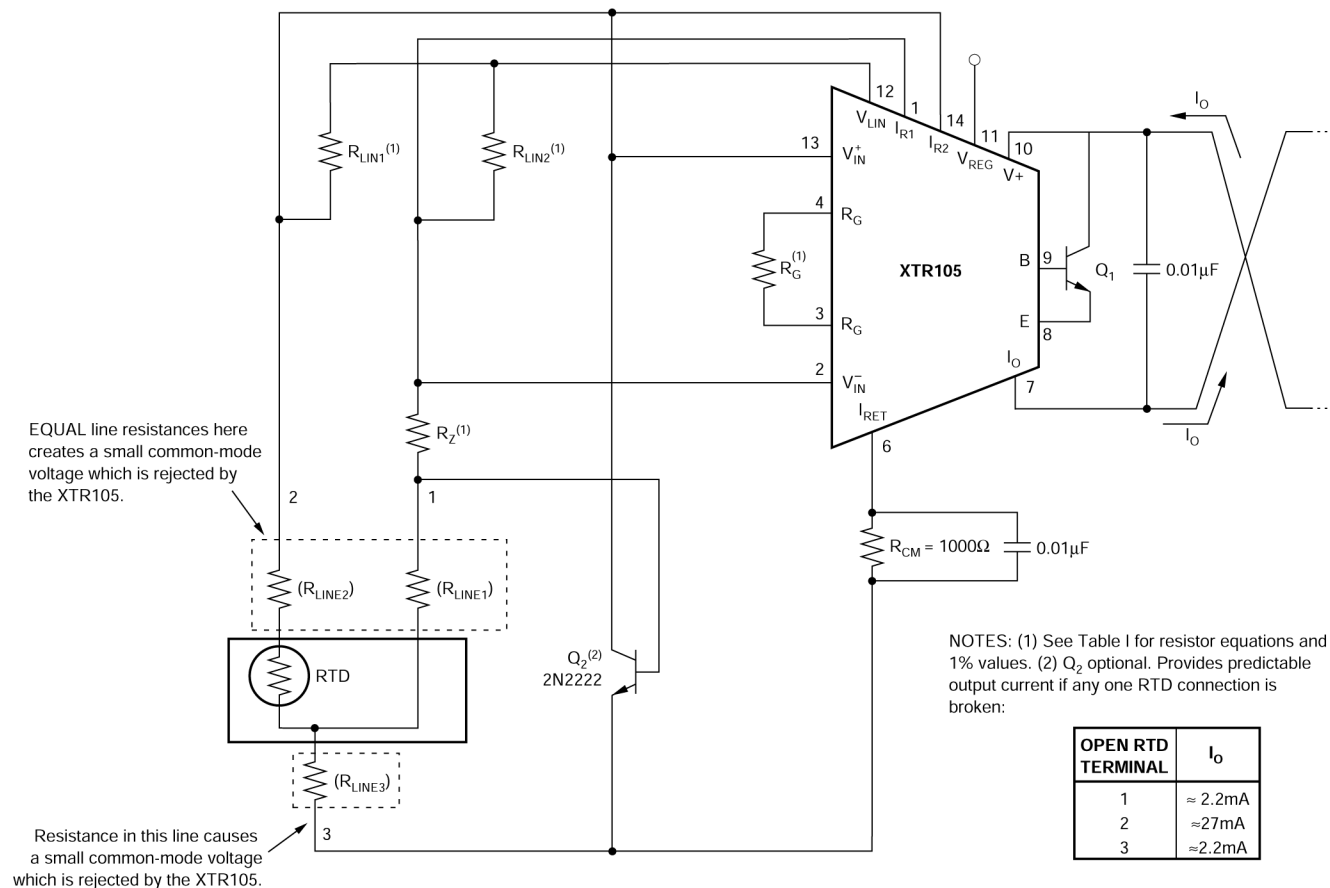
The  $V_{REG}$  pin provides an on-chip voltage source of approximately 5.1V and is designed for powering external input circuitry (as shown in Figure 6-2). This source is a moderately accurate voltage reference, and is not the same reference used to set the 800 $\mu$ A current references.  $V_{REG}$  is capable of sourcing approximately 1mA of current. Exceeding 1mA can affect the 4mA zero output.



**Figure 6-2. Thermocouple Low Offset, Low Drift Loop Measurement With Diode Cold Junction Compensation**

### 6.3.3 Open-Circuit Protection

Optional transistor  $Q_2$  in Figure 6-3 provides predictable behavior with open-circuit RTD connections. If any one of the three RTD connections is broken, the XTR105 output current goes to either the high current limit ( $\approx 27\text{mA}$ ) or low current limit ( $\approx 2.2\text{mA}$ ). This state is easily detected as an out-of-range condition.



**Figure 6-3. Remotely Located RTDs With a 3-Wire Connection**

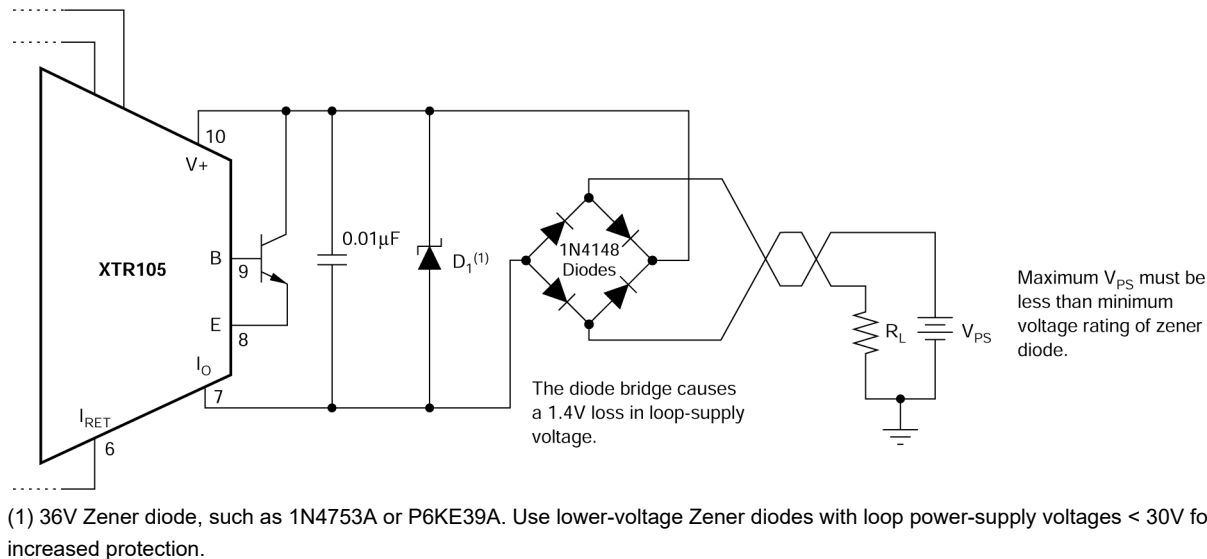
### 6.3.4 Reverse-Voltage Protection

The XTR105 low compliance rating (7.5V) permits the use of various voltage protection methods without compromising operating range. Figure 6-4 shows a diode bridge circuit that allows normal operation even when the voltage connection lines are reversed. The bridge causes a two diode drop (approximately 1.4V) loss in loop-supply voltage. This results in a compliance voltage of approximately 9V—satisfactory for most applications. If a 1.4V drop in loop supply is too much, a diode can be inserted in series with the loop-supply voltage and the  $V_+$  pin. This protects against reverse output connection lines with only a 0.7V loss in loop-supply voltage.

### 6.3.5 Surge Protection

Remote connections to current transmitters are sometimes subjected to voltage surges. Limit the maximum surge voltage applied to the XTR105 to the lowest practical value. Various zener diodes and surge clamping diodes are specially designed for this purpose. Select a clamp diode with as low a voltage rating as possible for best protection. For example, a 36V protection diode allows proper transmitter operation at normal loop voltages, yet provides an appropriate level of protection against voltage surges. The XTR105 is specified to an absolute maximum loop voltage of 40V.

Most surge protection zener diodes have a diode characteristic in the forward direction that conducts excessive current, possibly damaging receiving-side circuitry, if the loop connections are reversed. If a surge protection diode is used, use a series diode or diode bridge for protection against reversed connections.



**Figure 6-4. Reverse Voltage Operation and Overvoltage Surge Protection**

### 6.4 Device Functional Modes

The device has one mode of operation that applies when operated within the *Recommended Operating Conditions*.

## 7 Application and Implementation

### Note

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes, as well as validating and testing their design implementation to confirm system functionality.

### 7.1 Application Information

[Figure 7-1](#) shows the basic connection diagram for the XTR105. The loop power supply,  $V_{PS}$ , provides power for all circuitry. Output loop current is measured as a voltage across the series load resistor,  $R_L$ .

Two matched 0.8mA current sources drive the RTD and zero-setting resistor,  $R_Z$ . The instrumentation amplifier input of the XTR105 measures the voltage difference between the RTD and  $R_Z$ . The value of  $R_Z$  is chosen to be equal to the resistance of the RTD at the low-scale (minimum) measurement temperature.  $R_Z$  can be adjusted to achieve 4mA output at the minimum measurement temperature to correct for input offset voltage and reference current mismatch of the XTR105.

$R_{CM}$  provides an additional voltage drop to bias the inputs of the XTR105 within the common-mode input range. Bypass  $R_{CM}$  with a 0.01μF capacitor to minimize common-mode noise. Resistor  $R_G$  sets the gain of the instrumentation amplifier according to the desired temperature range.  $R_{LIN1}$  provides 2nd-order linearization correction to the RTD, typically achieving a 40:1 improvement in linearity. An additional resistor is required for 3-wire RTD connections (see [Figure 6-3](#)).

The transfer function through the complete instrumentation amplifier and voltage-to-current converter is:

$$I_O = 4mA + V_{IN} \times (40 / R_G)$$

( $V_{IN}$  in volts,  $R_G$  in ohms)

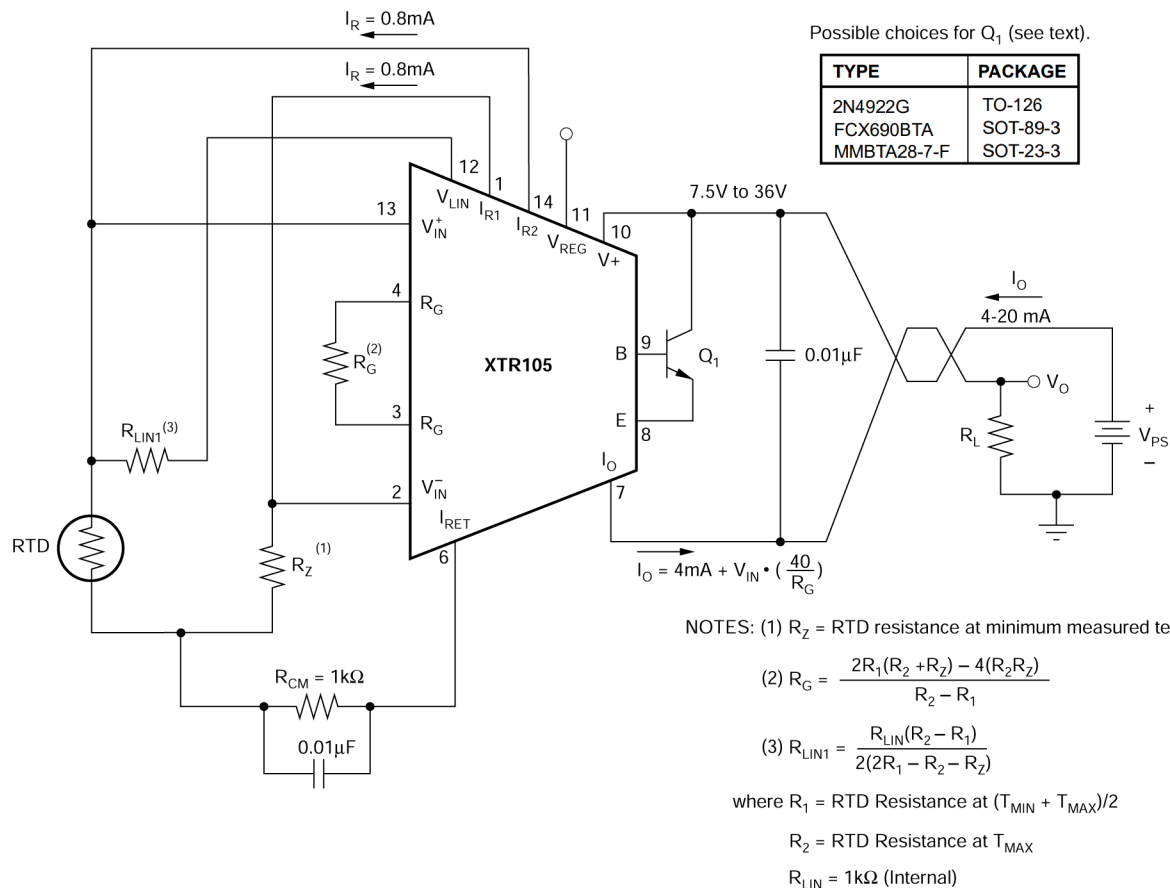
where  $V_{IN}$  is the differential input voltage.

A negative input voltage,  $V_{IN}$ , causes the output current to be less than 4mA. Increasingly negative  $V_{IN}$  causes the output current to limit at approximately 2.2mA. See also typical characteristic *Under-Scale Current vs Temperature*.

Increasingly positive input voltage (greater than the full-scale input) produces increasing output current according to the transfer function, up to the output current limit of approximately 27mA. See also typical characteristic *Over-Scale Current vs Temperature*.

As evident from the transfer function, if no  $R_G$  is used the gain is zero and the output is simply the XTR105's zero current. The value of  $R_G$  varies slightly for 2-wire RTD and 3-wire RTD connections with linearization.  $R_G$  can be calculated from the equations given in [Figure 7-1](#) (2-wire RTD connection) and [Table 7-1](#) (3-wire RTD connection).

The  $I_{RET}$  pin is the return path for all current from the current sources and  $V_{REG}$ . The  $I_{RET}$  pin allows any current used in external circuitry to be sensed by the XTR105 and to be included in the output current without causing an error.



**Figure 7-1. Basic 2-Wire RTD Temperature Measurement Circuit With Linearization**



**Table 7-1.  $R_Z$ ,  $R_G$ ,  $R_{LIN1}$ , and  $R_{LIN2}$  Standard 1% Resistor Values for 3-Wire Pt100 RTD Connection With Linearization**

MEASUREMENT TEMPERATURE SPAN $\Delta T$ (°C)										
$T_{MIN}$	100°C	200°C	300°C	400°C	500°C	600°C	700°C	800°C	900°C	1000°C
–200°C	18.7/86.6 15000 16500	18.7/169 9760 11500	18.7/255 8060 10000	18.7/340 6650 8870	18.7/422 5620 7870	18.7/511 4750 7150	18.7/590 4020 6420	18.7/665 3480 5900	18.7/750 3090 5360	18.7/845 2740 4990
–100°C	60.4/80.6 27400 29400	60.4/162 15400 17800	60.4/243 10500 13000	60.4/324 7870 10200	60.4/402 6040 8660	60.4/487 4990 7500	60.4/562 4220 6490	60.4/649 3570 5900	60.4/732 3090 5360	
0°C	100/78.7 33200 35700	100/158 16200 18700	100/237 10500 13000	100/316 7680 10000	100/392 6040 8250	100/475 4870 7150	100/549 4020 6340	100/634 3480 5620		
100°C	137/75 31600 34000	137/150 15400 17800	137/226 10200 12400	137/301 7500 9760	137/383 5760 8060	137/453 4750 6810	137/536 3920 6040			
200°C	174/73.2 30900 33200	174/147 15000 17400	174/221 9760 12100	174/294 7150 9310	174/365 5620 7680	174/442 4530 6490				
300°C	210/71.5 30100 32400	210/143 14700 16500	210/215 9530 11500	210/287 6980 8870	210/357 5360 7320					
400°C	249/68.1 28700 30900	249/137 14000 16200	249/205 9090 11000	249/274 6650 8450						
500°C	280/66.5 28000 30100	280/133 13700 15400	280/200 8870 10500							
600°C	316/64.9 26700 28700	313/130 13000 14700								
700°C	348/61.9 26100 27400									
800°C	374/60.4 24900 26700									

$\left[ \begin{matrix} R_Z/R_G \\ R_{LIN1} \\ R_{LIN2} \end{matrix} \right]$

NOTE: The values listed in this table are 1% resistors (in  $\Omega$ ). Exact values may be calculated from the following equations:

$R_Z$  = RTD resistance at minimum measured temperature.

$$R_G = \frac{2(R_Z - R_1)(R_1 - R_Z)}{(R_2 - R_1)}$$

$$R_{LIN1} = \frac{R_{LIN}(R_2 - R_1)}{2(2R_1 - R_2 - R_Z)}$$

$$R_{LIN2} = \frac{(R_{LIN} + R_G)(R_2 - R_1)}{2(2R_1 - R_2 - R_Z)}$$

where:  $R_1$  = RTD resistance at  $(T_{MIN} + T_{MAX})/2$

$R_2$  = RTD resistance at  $T_{MAX}$

$R_{LIN}$  = 1k $\Omega$  (Internal)

#### EXAMPLE:

The measurement range is –100°C to +200°C for a 3-wire Pt100 RTD connection. Determine the values for  $R_Z$ ,  $R_G$ ,  $R_{LIN1}$ , and  $R_{LIN2}$ . Look up the values from the chart or calculate the values according to the equations provided.

#### METHOD 1: TABLE LOOK UP

For  $T_{MIN}$  = –100°C and  $\Delta T$  = –300°C, the 1% values are:

$$R_Z = 60.4\Omega \quad R_{LIN1} = 10.5k\Omega$$

$$R_G = 243\Omega \quad R_{LIN2} = 13k\Omega$$

#### METHOD 2: CALCULATION

**Step 1:** Determine  $R_Z$ ,  $R_1$ , and  $R_2$ .

$R_Z$  is the RTD resistance at the minimum measured temperature,  $T_{MIN}$  = –100°C. Using Equation 1 at right gives  $R_Z$  = 60.25 $\Omega$  (1% value is 60.4 $\Omega$ ).

$R_2$  is the RTD resistance at the maximum measured temperature,  $T_{MAX}$  = 200°C. Using Equation 2 at right gives  $R_2$  = 175.84 $\Omega$ .

$R_1$  is the RTD resistance at the midpoint measured temperature,  $T_{MID}$  =  $(T_{MIN} + T_{MAX})/2$  = 50°C.  $R_1$  is NOT the average of  $R_Z$  and  $R_2$ . Using Equation 2 at right gives  $R_1$  = 119.40 $\Omega$ .

**Step 2:** Calculate  $R_G$ ,  $R_{LIN1}$ , and  $R_{LIN2}$  using equations above.

$$R_G = 242.3\Omega \text{ (1% value is 243}\Omega\text{)}$$

$$R_{LIN1} = 10.413k\Omega \text{ (1% value is 10.5k}\Omega\text{)}$$

$$R_{LIN2} = 12.936k\Omega \text{ (1% value is 13k}\Omega\text{)}$$

#### Calculation of Pt100 Resistance Values

(according to DIN IEC 751)

(Equation 1) Temperature range from –200°C to 0°C:  

$$R(T) = 100 [1 + 3.90802 \cdot 10^{-3} \cdot T - 0.5802 \cdot 10^{-6} \cdot T^2 - 4.27350 \cdot 10^{-12} (T - 100) T^3]$$

(Equation 2) Temperature range from 0°C to +850°C:  

$$R(T) = 100 (1 + 3.90802 \cdot 10^{-3} \cdot T - 0.5802 \cdot 10^{-6} \cdot T^2)$$

where:  $R(T)$  is the resistance in  $\Omega$  at temperature  $T$ .  
 $T$  is the temperature in °C.

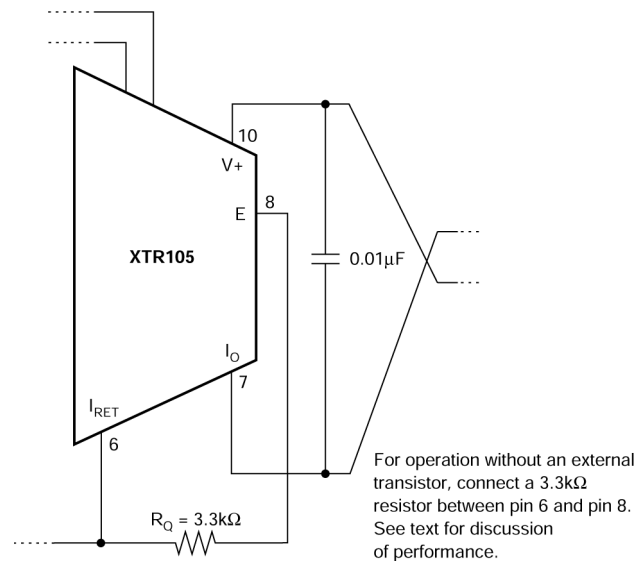
NOTE: Most RTD manufacturers provide reference tables for resistance values at various temperatures.

### 7.1.1 External Transistor

Transistor Q<sub>1</sub> conducts the majority of the signal-dependent 4-20mA loop current. Using an external transistor isolates the majority of the power dissipation from the precision input and reference circuitry of the XTR105, maintaining excellent accuracy.

The external transistor is inside a feedback loop; therefore, the transistor characteristics are not critical. Requirements are:  $V_{CEO} = 45V$  min,  $\beta = 40$  min, and  $P_D = 800mW$ . Power dissipation requirements can be lower if the loop power-supply voltage is less than 36V. Some possible choices for Q<sub>1</sub> are listed in [Figure 7-1](#).

The XTR105 operates without this external transistor; however, accuracy is somewhat degraded as a result of the internal power dissipation and resulting self-heating. Operation without Q<sub>1</sub> is not recommended for extended temperature ranges. A resistor ( $R = 3.3k\Omega$ ) connected between the I<sub>RET</sub> pin and the E (emitter) pin is advised for operation below 0°C without Q<sub>1</sub> to support the full 20mA full-scale output, especially with V<sub>+</sub> near 7.5V.



**Figure 7-2. Operation Without an External Transistor**

### 7.1.2 Loop Power Supply

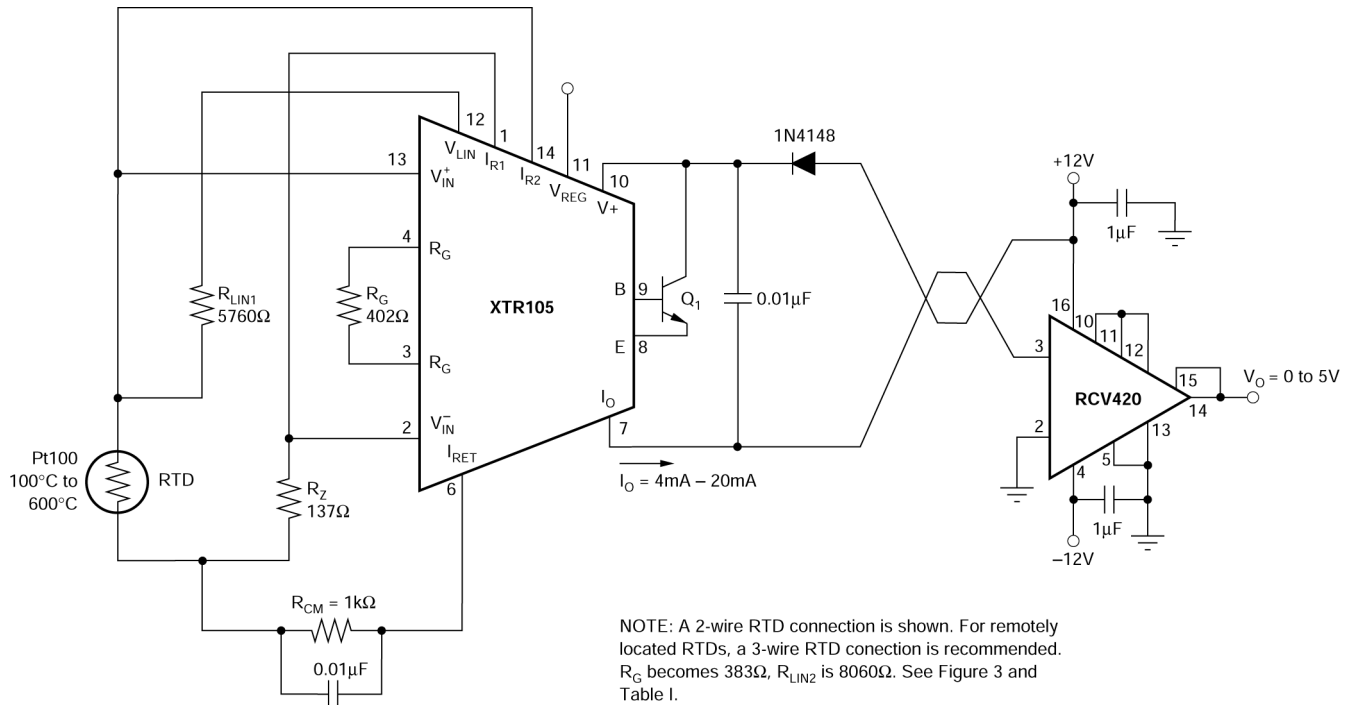
The voltage applied to the XTR105, V<sub>+</sub>, is measured with respect to the I<sub>O</sub> connection, pin 7. V<sub>+</sub> can range from 7.5V to 36V. The loop-supply voltage, V<sub>PS</sub>, differs from the voltage applied to the XTR105 according to the voltage drop on the current sensing resistor, R<sub>L</sub> (plus any other voltage drop in the line).

If a low loop-supply voltage is used, R<sub>L</sub> (including the loop wiring resistance) must be made a relatively low value so that V<sub>+</sub> remains 7.5V or greater for the maximum loop current of 20mA:

$$R_L \text{ max} = \left( \frac{(V_+) - 7.5V}{20mA} \right) - R_{\text{WIRING}}$$

For loop currents up to 30mA, design for V<sub>+</sub> equal or greater than 7.5V to allow for out-of-range input conditions.

The low operating voltage (7.5V) of the XTR105 allows operation directly from personal computer power supplies (12V ±5%). When used with the RCV420 current loop receiver (see [Figure 7-3](#)), the load resistor voltage drop is limited to 3V.



**Figure 7-3. ±12V Powered Transmitter-Receiver Loop**

### 7.1.3 2-Wire and 3-Wire RTD Connections

In [Figure 7-1](#), the RTD can be located remotely simply by extending the two connections to the RTD. With this remote 2-wire connection to the RTD, line resistance introduces error. This error can be partially corrected by adjusting the values of  $R_Z$ ,  $R_G$ , and  $R_{LIN1}$ .

A better method for remotely located RTDs is the 3-wire RTD connection (see [Figure 6-3](#)). This circuit offers improved accuracy.  $R_Z$ 's current is routed through a third wire to the RTD. Assuming line resistance is equal in RTD lines 1 and 2, this produces a small common-mode voltage that is rejected by the XTR105. A second resistor,  $R_{LIN2}$ , is required for linearization.

Note that although the 2-wire and 3-wire RTD connection circuits are very similar, the gain-setting resistor,  $R_G$ , has slightly different equations:

$$\text{2-wire: } R_G = \frac{2R_1(R_2 + R_Z) - 4(R_2R_Z)}{R_2 - R_1}$$

$$\text{3-wire: } R_G = \frac{2(R_2 - R_Z)(R_1 - R_Z)}{R_2 - R_1}$$

where

- $R_Z$  = RTD resistance at  $T_{MIN}$
- $R_1$  = RTD resistance at  $(T_{MIN} + T_{MAX}) / 2$
- $R_2$  = RTD resistance at  $T_{MAX}$

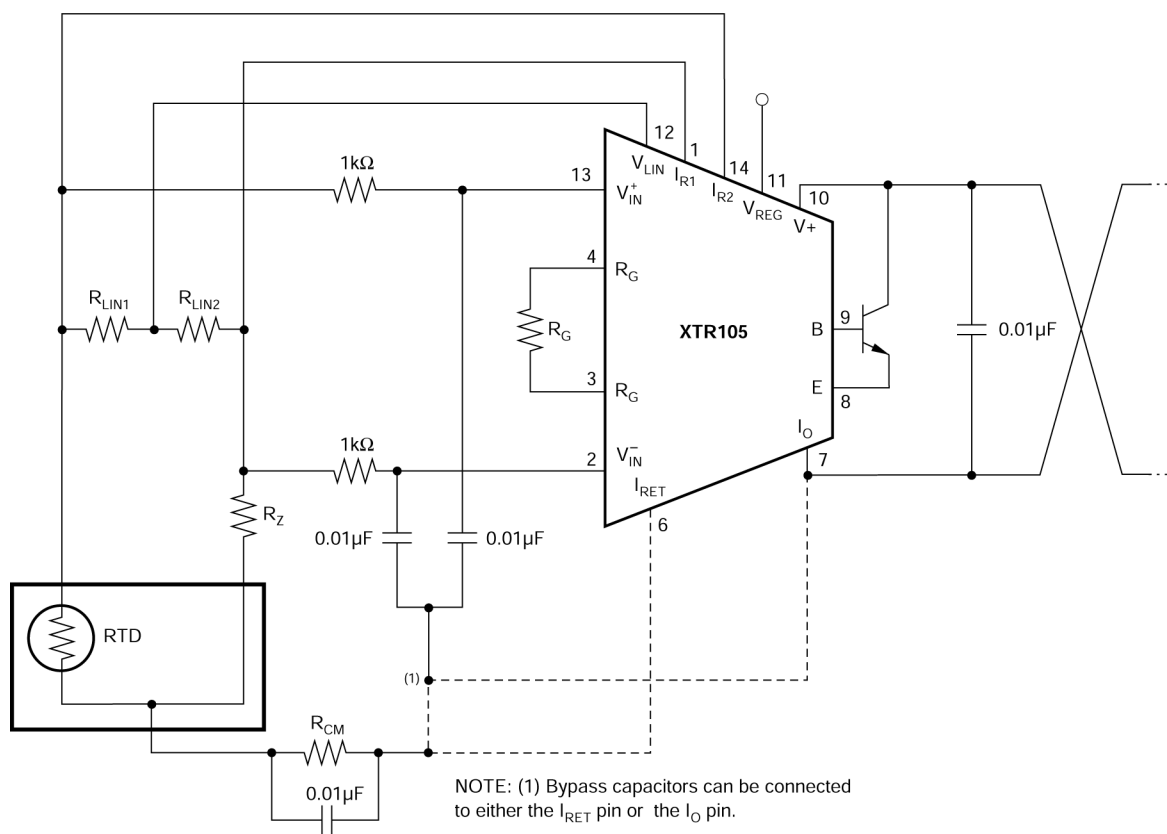
To maintain good accuracy, use at least 1% (or better) resistors for  $R_G$ . [Table 7-1](#) provides standard 1%  $R_G$  resistor values for a 3-wire Pt100 RTD connection with linearization.

#### 7.1.4 Radio Frequency Interference

The long wire lengths of current loops invite radio frequency (RF) interference. RF can be rectified by the sensitive input circuitry of the XTR105, causing errors. This generally appears as an unstable output current that varies with the position of loop supply or input wiring.

If the RTD sensor is remotely located, the interference can enter at the input terminals. For integrated transmitter assemblies with short connections to the sensor, the interference more likely comes from the current loop connections.

Bypass capacitors on the input reduce or eliminate this input interference. Connect these bypass capacitors to the  $I_{RET}$  terminal (see [Figure 7-4](#)). Although the dc voltage at the  $I_{RET}$  terminal is not equal to 0V (at the loop supply,  $V_{PS}$ ), this circuit point can be considered the transmitter *ground*. The 0.01 $\mu$ F capacitor connected between  $V+$  and  $I_O$  can help minimize output interference.



### Figure 7-4. Input Bypassing Technique With Linearization

### 7.1.5 Error Analysis

Many applications require adjustment of initial errors. Input offset and reference current mismatch errors can be corrected by adjustment of the zero resistor,  $R_Z$ . Adjusting the gain-setting resistor,  $R_G$ , corrects any errors associated with gain.

**Table 7-2** shows how to calculate the effect of various error sources on the circuit accuracy. A sample error calculation for a typical RTD measurement circuit (Pt100 RTD, 200°C measurement span) is provided. The results reveal the XTR105 excellent accuracy, in this case 1.1% unadjusted. Adjusting resistors  $R_G$  and  $R_Z$  for gain and offset errors improves circuit accuracy to 0.32%. These are worst-case errors; maximum values were used in the calculations and all errors were assumed to be positive (additive). The XTR105 achieves performance that is difficult to obtain with discrete circuitry and requires less space.

**Table 7-2. Error Calculation**

SAMPLE ERROR CALCULATION				
RTD value at 4mA output (R <sub>RTD MIN</sub> ): 100Ω				
RTD measurement range: 200°C				
Ambient temperature range (ΔT <sub>A</sub> ): 20°C				
Supply voltage change (ΔV <sub>+</sub> ): 5V				
Common-mode voltage change (ΔCM): 0.1V				
ERROR SOURCE	ERROR EQUATION	SAMPLE ERROR CALCULATION <sup>(1)</sup>	ERROR (ppm of Full Scale)	
			UNADJ.	ADJUST.
INPUT				
Input offset voltage	V <sub>OS</sub> / (V <sub>IN MAX</sub> ) × 10 <sup>6</sup>	100μV / (800μA × 0.38Ω/°C × 200°C) × 10 <sup>6</sup>	1645	0
vs common-mode	CMRR · ΔCM/(V <sub>IN MAX</sub> ) × 10 <sup>6</sup>	50μV/V × 0.1V / (800μA × 0.38Ω/°C × 200°C) × 10 <sup>6</sup>	82	82
Input bias current	I <sub>B</sub> / I <sub>REF</sub> × 10 <sup>6</sup>	0.025μA / 800μA × 10 <sup>6</sup>	31	0
Input offset current	I <sub>OS</sub> × R <sub>RTD MIN</sub> / (V <sub>IN MAX</sub> ) × 10 <sup>6</sup>	3nA × 100Ω / (800μA × 0.38Ω/°C × 200°C) × 10 <sup>6</sup>	5	0
Total Input Error:			1763	82
EXCITATION				
Current reference accuracy	I <sub>REF</sub> accuracy (%) / 100% × 10 <sup>6</sup>	0.2% / 100% × 10 <sup>6</sup>	2000	0
vs supply	(I <sub>REF</sub> vs V <sub>+</sub> ) × ΔV <sub>+</sub>	25ppm/V × 5V	125	125
Current reference matching	I <sub>REF</sub> matching (%) / 100% × 800μA × R <sub>RTD MIN</sub> / (V <sub>IN MAX</sub> ) × 10 <sup>6</sup>	0.1% / 100% × 800μA × 100Ω / (800μA × 0.38Ω/°C × 200°C) × 10 <sup>6</sup>	1316	0
vs supply	(I <sub>REF</sub> matching vs V <sub>+</sub> ) × ΔV <sub>+</sub> × R <sub>RTD MIN</sub> / (V <sub>IN MAX</sub> )	10ppm/V × 5V × 800μA × 100Ω / (800μA × 0.38Ω/°C × 200°C)	66	66
Total Excitation Error:			3507	191
GAIN				
Span	Span error (%) / 100% × 10 <sup>6</sup>	0.2% / 100% × 10 <sup>6</sup>	2000	0
Nonlinearity	Nonlinearity (%) / 100% × 10 <sup>6</sup>	0.01% / 100% × 10 <sup>6</sup>	100	100
Total Gain Error:			2100	100
OUTPUT				
Zero output	(I <sub>ZERO</sub> – 4mA) / 16000μA × 10 <sup>6</sup>	25μA / 16000μA × 10 <sup>6</sup>	1563	0
vs supply	(I <sub>ZERO</sub> vs V <sub>+</sub> ) × ΔV <sub>+</sub> / 16000μA × 10 <sup>6</sup>	0.2μA/V × 5V / 16000μA × 10 <sup>6</sup>	63	63
Total Output Error:			1626	63
DRIFT (ΔT <sub>A</sub> = 20°C)				
Input offset voltage	Drift × ΔT <sub>A</sub> / (V <sub>IN MAX</sub> ) × 10 <sup>6</sup>	1.5μV/°C × 20°C / (800μA × 0.38Ω/°C × 200°C) × 10 <sup>6</sup>	493	493
Input bias current (typical)	Drift × ΔT <sub>A</sub> / 800μA × 10 <sup>6</sup>	20pA/°C × 20°C / 800μA × 10 <sup>6</sup>	0.5	0.5
Input offset current (typical)	Drift × ΔT <sub>A</sub> × R <sub>RTD MIN</sub> / (V <sub>IN MAX</sub> ) × 10 <sup>6</sup>	5pA/°C × 20°C × 100W / (800μA × 0.38Ω/°C × 200°C) × 10 <sup>6</sup>	0.2	0.2
Current reference accuracy	Drift · ΔT <sub>A</sub>	35ppm/°C × 20°C	700	700
Current reference matching	Drift × ΔT <sub>A</sub> × 800μA × R <sub>RTD MIN</sub> / (V <sub>IN MAX</sub> )	15ppm/°C × 20°C × 800μA × 100Ω / (800μA × 0.38Ω/°C × 200°C)	395	395
Span	Drift × ΔT <sub>A</sub>	25ppm/°C × 20°C	500	500
Zero output	Drift × ΔT <sub>A</sub> / 16000μA × 10 <sup>6</sup>	0.5μA/°C × 20°C / 16000μA × 10 <sup>6</sup>	626	626
Total Drift Error:			2715	2715
NOISE (0.1Hz to 10Hz, typical)				
Input offset voltage	V <sub>n</sub> / (V <sub>IN MAX</sub> ) × 10 <sup>6</sup>	0.6μV / (800μA × 0.38Ω/°C × 200°C) × 10 <sup>6</sup>	10	10
Current reference	I <sub>REF</sub> noise × R <sub>RTD MIN</sub> / (V <sub>IN MAX</sub> ) × 10 <sup>6</sup>	3nA × 100Ω / (800μA × 0.38Ω/°C × 200°C) × 10 <sup>6</sup>	5	5
Zero output	I <sub>ZERO</sub> noise / 16000μA × 10 <sup>6</sup>	0.03μA / 16000μA × 10 <sup>6</sup>	2	2
Total Noise Error:			17	17
TOTAL ERROR:			11728 (1.17%)	3168 (0.32%)

(1) All errors are minimum and maximum, and referred to input, unless otherwise stated.

## 7.2 Typical Applications

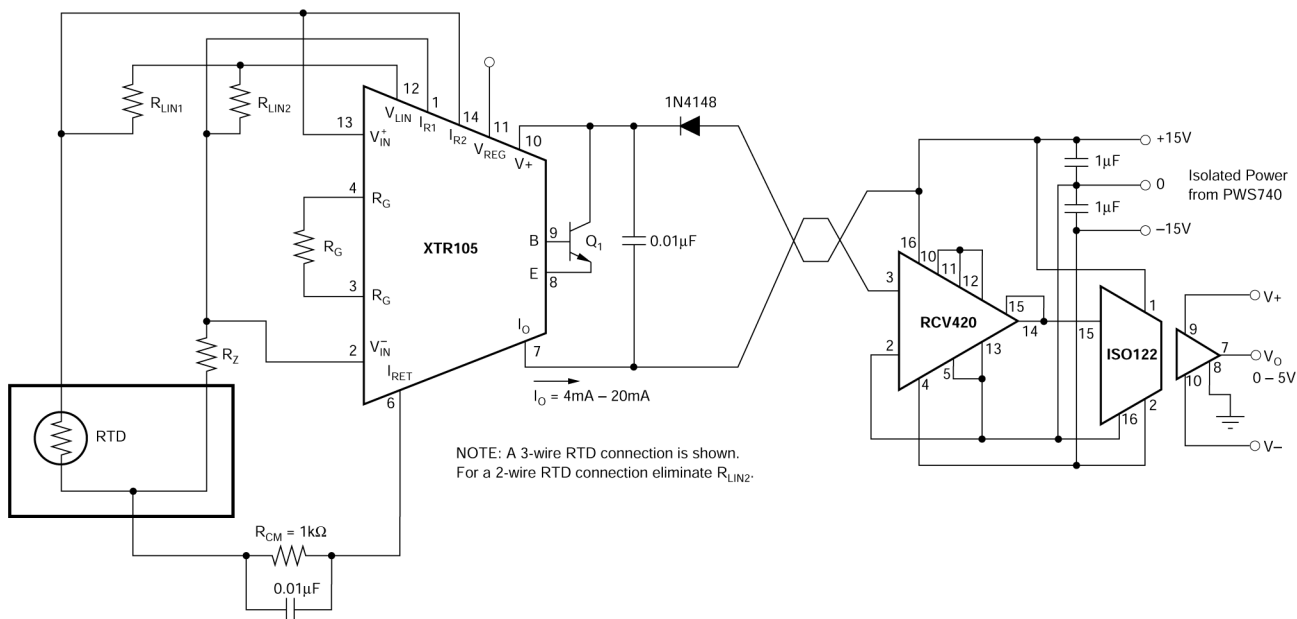


Figure 7-5. Isolated Transmitter-Receiver Loop

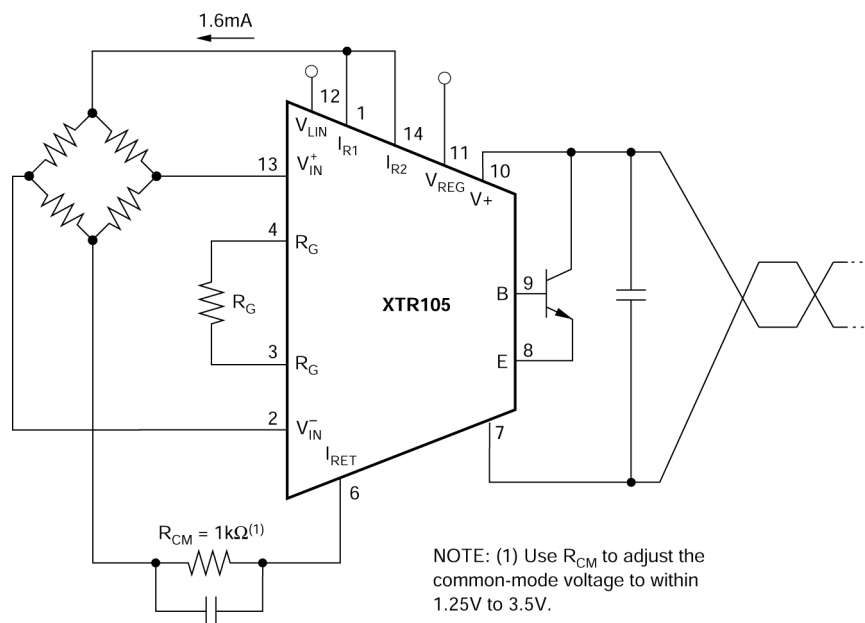


Figure 7-6. Bridge Input, Current Excitation

## 7.3 Layout

### 7.3.1 Layout Guidelines

The XTR105 is typically used with an external transistor ( $Q_1$ ) to regulate the power dissipation of the 4-20mA loop. This allows the resulting localized self-heating to be distanced from the precision circuitry of the XTR105 and reduces over-temperature drift errors.

The XTR105 can be used without the  $Q_1$  transistor if the application requirements do not lead to violation of the device *Absolute Maximum Requirements*, such as the maximum junction temperature. Calculate the peak power dissipation and multiply by thermal resistance to determine the associated junction temperature rise. Minimize overheat conditions for reliable long-term operation.

Place supply bypass capacitors close to the package and make connections with low-impedance conductors. Reduce trace lengths for  $R_G$  to minimize coupled environmental noise. If the loop power supply is electrically noisy, implement filtering using decoupling capacitors and small resistors or dampening inductors in series with  $V+$ .

## 8 Device and Documentation Support

TI offers an extensive line of development tools. Tools and software to evaluate the performance of the device, generate code, and develop solutions are listed below.

### 8.1 Documentation Support

#### 8.1.1 Related Documentation

For related documentation see the following:

- Texas Instruments, [Special Function Amplifiers Precision Labs video series](#) on Current Loop Transmitters
- Texas Instruments, [Analog Linearized 3-Wire PT100 RTD to 2-Wire 4-20mA Current Loop Transmitter reference design](#) with XTR105
- Texas Instruments, [Analog Linearization of Resistance Temperature Detectors](#) technical article
- Texas Instruments, [A Basic Guide to RTD Measurements](#) application note

### 8.2 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on [ti.com](#). Click on *Notifications* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

### 8.3 Support Resources

TI E2E™ [support forums](#) are an engineer's go-to source for fast, verified answers and design help — straight from the experts. Search existing answers or ask your own question to get the quick design help you need.

Linked content is provided "AS IS" by the respective contributors. They do not constitute TI specifications and do not necessarily reflect TI's views; see TI's [Terms of Use](#).

### 8.4 Trademarks

TI E2E™ is a trademark of Texas Instruments.

All trademarks are the property of their respective owners.

### 8.5 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

### 8.6 Glossary

[TI Glossary](#) This glossary lists and explains terms, acronyms, and definitions.

## 9 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

Changes from Revision B (August 2004) to Revision C (October 2024)	Page
• Added the <i>Pin Configuration and Functions</i> , <i>Specifications</i> , <i>ESD Ratings</i> , <i>Recommended Operating Conditions</i> , <i>Thermal Information</i> , <i>Detailed Description</i> , <i>Overview</i> , <i>Functional Block Diagram</i> , <i>Feature Description</i> , <i>Device Functional Modes</i> , <i>Application and Implementation</i> , <i>Typical Applications</i> , <i>Layout</i> , <i>Layout Guidelines</i> , <i>Device and Documentation Support</i> , and <i>Mechanical, Packaging, and Orderable Information</i> sections.....	1
• Added end equipments in <i>Applications</i> .....	1
• Updated the numbering format for tables, figures, and cross-references throughout the document.....	1
• Added <i>Pin Functions</i> table.....	3
• Moved operating and storage temperature parameters from <i>Electrical Characteristics</i> to <i>Absolute Maximum Ratings</i> .....	4



• Changed minimum operating temperature from –55°C to –40°C in <i>Absolute Maximum Ratings</i> .....	4
• Moved specified temperature and power-supply parameters from <i>Electrical Characteristics</i> to <i>Recommended Operating Conditions</i> .....	4
• Deleted thermal resistance, $\theta_{JA}$ parameters in <i>Electrical Characteristics</i> and replaced with detailed thermal model parameters in <i>Thermal Information</i> .....	4
• Updated formatting of <i>Electrical Characteristics</i> table.....	5
• Changed Voltage accuracy vs temperature typical specification from $\pm 0.2\text{mV}/^\circ\text{C}$ to $\pm 0.5\text{mV}/^\circ\text{C}$ in <i>Electrical Characteristics</i> .....	5
• Updated Figure 5-2, <i>Step Response</i> .....	7
• Updated Figure 5-8, <i>Zero Output and Reference Current Noise vs Frequency</i> .....	7
• Changed description of maximum loop-supply voltage to specified absolute maximum rating in <i>Surge Protection</i> .....	14
• Updated suggested Zener diode part numbers in Figure 6-4, <i>Reverse Voltage Operation and Overvoltage Surge Protection</i> .....	14
• Updated suggested transistor part numbers in Figure 7-1, <i>Basic 2-Wire RTD Temperature Measurement Circuit with Linearization</i> .....	15
• Moved <i>Adjusting Initial Errors</i> into <i>Error Analysis</i> section .....	20

## 10 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

## PACKAGING INFORMATION

Orderable Device	Status (1)	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead finish/ Ball material (6)	MSL Peak Temp (3)	Op Temp (°C)	Device Marking (4/5)	Samples
XTR105P	ACTIVE	PDIP	N	14	25	RoHS & Green	Call TI	N / A for Pkg Type	-40 to 85	XTR105P A	<a href="#">Samples</a>
XTR105PA	ACTIVE	PDIP	N	14	25	RoHS & Green	Call TI	N / A for Pkg Type	-40 to 85	XTR105P A	<a href="#">Samples</a>
XTR105UA	OBSOLETE	SOIC	D	14		TBD	Call TI	Call TI	-40 to 85	XTR105U A	
XTR105UA/2K5	ACTIVE	SOIC	D	14	2500	RoHS & Green	NIPDAU	Level-3-260C-168 HR	-40 to 85	(XTR105U, XTR105UA ) A	<a href="#">Samples</a>

(1) The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) **RoHS:** TI defines "RoHS" to mean semiconductor products that are compliant with the current EU RoHS requirements for all 10 RoHS substances, including the requirement that RoHS substance do not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, "RoHS" products are suitable for use in specified lead-free processes. TI may reference these types of products as "Pb-Free".

**RoHS Exempt:** TI defines "RoHS Exempt" to mean products that contain lead but are compliant with EU RoHS pursuant to a specific EU RoHS exemption.

**Green:** TI defines "Green" to mean the content of Chlorine (Cl) and Bromine (Br) based flame retardants meet JS709B low halogen requirements of <=1000ppm threshold. Antimony trioxide based flame retardants must also meet the <=1000ppm threshold requirement.

(3) MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

(4) There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

(5) Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead finish/Ball material - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead finish/Ball material values may wrap to two lines if the finish value exceeds the maximum column width.

**Important Information and Disclaimer:** The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

## TAPE AND REEL INFORMATION



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
XTR105UA/2K5	SOIC	D	14	2500	330.0	16.4	6.5	9.0	2.1	8.0	16.0	Q1
XTR105UA/2K5	SOIC	D	14	2500	330.0	16.4	6.5	9.0	2.1	8.0	16.0	Q1

## TAPE AND REEL BOX DIMENSIONS



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
XTR105UA/2K5	SOIC	D	14	2500	356.0	356.0	35.0
XTR105UA/2K5	SOIC	D	14	2500	353.0	353.0	32.0

## TUBE

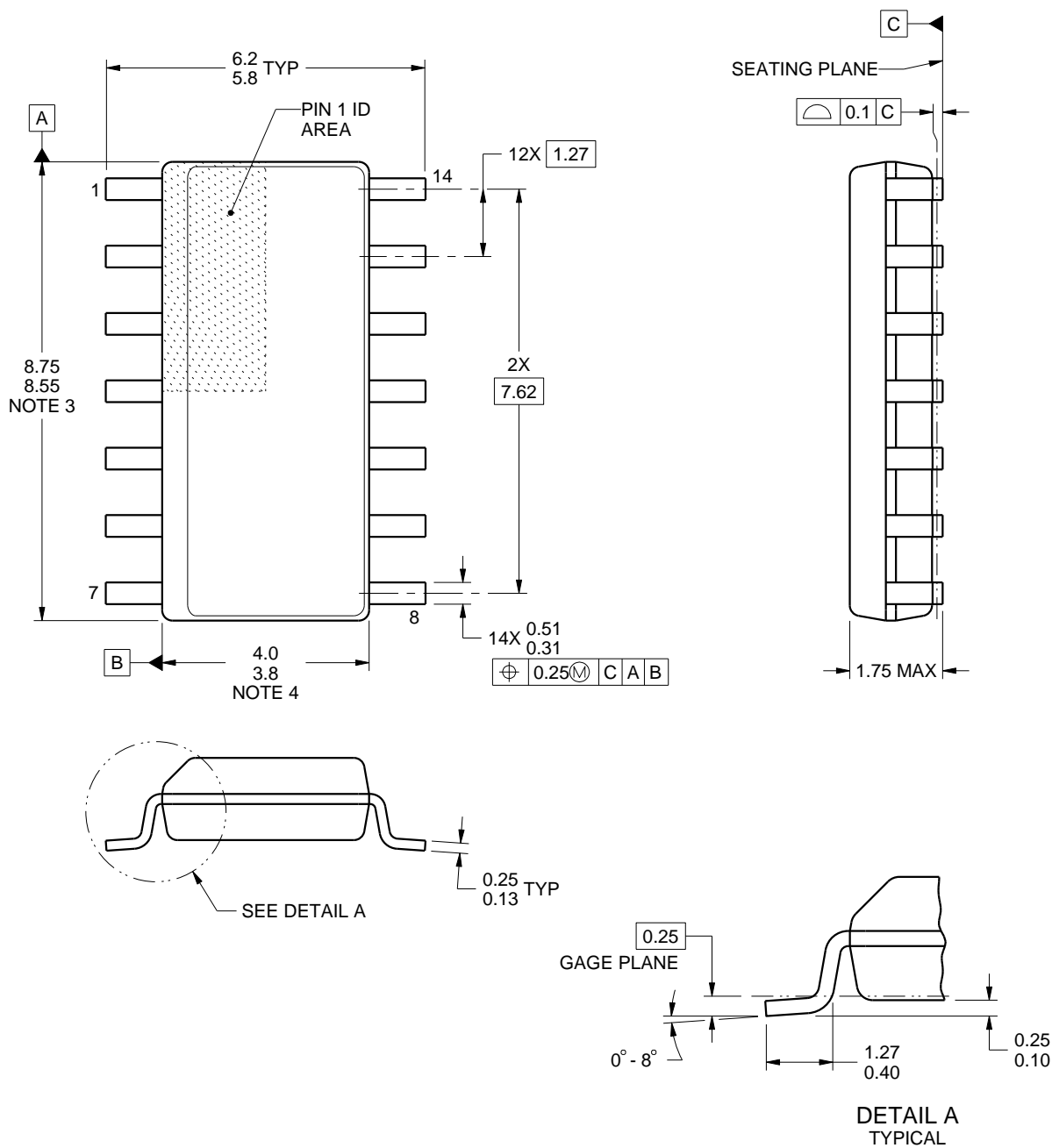


\*All dimensions are nominal

Device	Package Name	Package Type	Pins	SPQ	L (mm)	W (mm)	T (μm)	B (mm)
XTR105P	N	PDIP	14	25	506	13.97	11230	4.32
XTR105PA	N	PDIP	14	25	506	13.97	11230	4.32

**D0014A****PACKAGE OUTLINE****SOIC - 1.75 mm max height**

SMALL OUTLINE INTEGRATED CIRCUIT



4220718/A 09/2016

**NOTES:**

1. All linear dimensions are in millimeters. Dimensions in parenthesis are for reference only. Dimensioning and tolerancing per ASME Y14.5M.
2. This drawing is subject to change without notice.
3. This dimension does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.15 mm, per side.
4. This dimension does not include interlead flash. Interlead flash shall not exceed 0.43 mm, per side.
5. Reference JEDEC registration MS-012, variation AB.

# EXAMPLE BOARD LAYOUT

D0014A

SOIC - 1.75 mm max height

SMALL OUTLINE INTEGRATED CIRCUIT



LAND PATTERN EXAMPLE  
SCALE:8X



SOLDER MASK DETAILS

4220718/A 09/2016

NOTES: (continued)

6. Publication IPC-7351 may have alternate designs.

7. Solder mask tolerances between and around signal pads can vary based on board fabrication site.



## EXAMPLE STENCIL DESIGN

D0014A

SOIC - 1.75 mm max height

SMALL OUTLINE INTEGRATED CIRCUIT



SOLDER PASTE EXAMPLE  
BASED ON 0.125 mm THICK STENCIL  
SCALE:8X

4220718/A 09/2016

NOTES: (continued)

8. Laser cutting apertures with trapezoidal walls and rounded corners may offer better paste release. IPC-7525 may have alternate design recommendations.
9. Board assembly site may have different recommendations for stencil design.

N (R-PDIP-T\*\*)

16 PINS SHOWN

## PLASTIC DUAL-IN-LINE PACKAGE



PINS ** DIM	14	16	18	20
A MAX	0.775 (19,69)	0.775 (19,69)	0.920 (23,37)	1.060 (26,92)
A MIN	0.745 (18,92)	0.745 (18,92)	0.850 (21,59)	0.940 (23,88)
MS-001 VARIATION	AA	BB	AC	AD



4040049/E 12/2002

NOTES:

- A. All linear dimensions are in inches (millimeters).  
B. This drawing is subject to change without notice.
-  Falls within JEDEC MS-001, except 18 and 20 pin minimum body length (Dim A).  
 The 20 pin end lead shoulder width is a vendor option, either half or full width.

## IMPORTANT NOTICE AND DISCLAIMER

TI PROVIDES TECHNICAL AND RELIABILITY DATA (INCLUDING DATA SHEETS), DESIGN RESOURCES (INCLUDING REFERENCE DESIGNS), APPLICATION OR OTHER DESIGN ADVICE, WEB TOOLS, SAFETY INFORMATION, AND OTHER RESOURCES "AS IS" AND WITH ALL FAULTS, AND DISCLAIMS ALL WARRANTIES, EXPRESS AND IMPLIED, INCLUDING WITHOUT LIMITATION ANY IMPLIED WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE OR NON-INFRINGEMENT OF THIRD PARTY INTELLECTUAL PROPERTY RIGHTS.

These resources are intended for skilled developers designing with TI products. You are solely responsible for (1) selecting the appropriate TI products for your application, (2) designing, validating and testing your application, and (3) ensuring your application meets applicable standards, and any other safety, security, regulatory or other requirements.

These resources are subject to change without notice. TI grants you permission to use these resources only for development of an application that uses the TI products described in the resource. Other reproduction and display of these resources is prohibited. No license is granted to any other TI intellectual property right or to any third party intellectual property right. TI disclaims responsibility for, and you will fully indemnify TI and its representatives against, any claims, damages, costs, losses, and liabilities arising out of your use of these resources.

TI's products are provided subject to [TI's Terms of Sale](#) or other applicable terms available either on [ti.com](#) or provided in conjunction with such TI products. TI's provision of these resources does not expand or otherwise alter TI's applicable warranties or warranty disclaimers for TI products.

TI objects to and rejects any additional or different terms you may have proposed.

Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265  
Copyright © 2024, Texas Instruments Incorporated